# INSTRUCTIONS and PARTS MANUAL

# MODULAR DRIVE SYSTEM

found on your machine nameplate.	ication information below for future reference. This information can be
Model Number:	
Serial Number:	
Date of Purchase	
Whenever you request replacement you have recorded above.	parts or information on this equipment, always supply the information

LIT-MDS-IPM-0808



BUG-O SYSTEMS

A DIVISION OF WELD TOOLING CORPORATION

 $\epsilon$ 

280 TECHNOLOGY DRIVE CANONSBURG, PENNSYLVANIA 15317-9564 USA PHONE: 1-412-331-1776 http://www.bugo.com FAX: 1-412-331-0383

# SAFETY

PROTECT YOURSELF AND OTHERS FROM SERIOUS INJURY OR DEATH.
KEEP CHILDREN AWAY. BE SURE THAT ALL INSTALLATION, OPERATION,
MAINTENANCE AND REPAIR PROCEDURES ARE PERFORMED ONLY BY
QUALIFIED INDIVIDUALS.



# ELECTRIC SHOCK can kill.

- The equipment is not waterproof. Using the unit in a wet environment may result in serious injury. Do not touch equipment when wet or standing in a wet location.
- The unused connectors have power on them. Always keep the unused connectors covered with the supplied protective panels. Operation of the machine without the protective panels may result in injury.
- 3) Never open the equipment without first unplugging the power cord or serious injury may result.
- 4) Verify the customer-supplied power connections are made in accordance with all applicable local and national electrical safety codes. If none exist, use International Electric Code (IEC) 950.
- 5) Never remove or bypass the equipment power cord ground. Verify the equipment is grounded in accor dance with all applicable local and national electrical safety codes. If none exist, use International Electric Code (IEC) 950.



#### READ INSTRUCTIONS.

Read the instruction manual before installing and using the equipment.



# EQUIPMENT DAMAGE POSSIBLE.

- Do not plug in the power cord without first verifying the equipment is OFF and the cord input voltage is the same as required by the machine or serious damage may result.
- Always verity both the pinion and wheels are fully engaged before applying power or equipment damage may occur.
- 3) Do not leave the equipment unattended.
- 4) Remove from the worksite and store in a safe location when not in use.



FALLING EQUIPMENT can cause serious personal injury and equipment damage.

Faulty or careless user installation is possible. As a result, never stand or walk underneath equipment.



MOVING PARTS can cause serious injury.

- Never try to stop the pinion from moving except by removing power or by using the STOP control.
- Do not remove any protective panels, covers or guards and operate equipment.

# HIGH FREQUENCY WARNINGS

SPECIAL PRECAUTIONS ARE REQUIRED WHEN USING PLASMA, TIG OR ANY WELDING PROCESS THAT USES HIGH FREQUENCY TO STRIKE AN ARC.



**WARNING:** HIGH FREQUENCY CAN EFFECT MACHINE OPERATION AND THEREFORE, WELD QUALITY.

Read the precautions below before installing and using the equipment.

#### PRECAUTIONS:

- 1) Some plasma or welding cables are strong sources of high frequency interference. NEVER lay a plasma or welding cable across the controls of the machine.
- Always physically separate the plasma or welding cable leads from the machine cables. For example, the plasma or welding cable leads should NEVER be bundled with a pendant cable or the machine power cord. Maximize the separation between any machine cables and the plasma or welding cables.
- 3) Strictly follow the grounding procedures specified for the plasma or welding unit. NOTE: Some plasma and welding units produce exceptionally large amounts of high frequency noise. They may require a grounding rod be driven into the earth within six feet (2 meters) of the plasma or welding unit to become compatible with an automatic cutting or welding process.
- 4) If the high frequency is produced using a spark gap, adjust the points so the gap is as small as possible. The larger the gap, the higher the voltage and the higher the interference.
- 5) Some plasma or welding units will inject high frequency interference into the AC power line. Use separate power line branches whenever possible to power the plasma or welding source and the machine. Do not plug them into the same outlet box.
- High frequency noise may enter the machine through the plasma or welding supply remote contactor leads. Some plasma and welding sources can produce noise spikes of up to several thousand volts. These sources are not compatible with automated cutting and welding equipment. It is recommended that the remote contactor leads on these plasma or welding sources not be connected to the machine. An alternate solution is to purchase a separate remote contactor isolation box.

# MODULAR DRIVE SYSTEM INSTRUCTIONS AND PARTS MANUAL

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Patents Pending

59 ..... Warranty

#### INTRODUCTION

The Modular Drive System is the only product in the industry that allows the user to custom configure one machine for various applications. The system consists of drives, plug-in control modules and carriages that are easily assembled. The modular design allows the operator to quickly upgrade or reconfigure the machine for straight line cutting and welding, stitch welding or weave welding. The system will run in any position using Aluminum Rigid Rail, Aluminum Semi-Flex Rail [with a minimum radius of 10' (2.32 m)], Bent Rigid Rail or Hi-Flex Rail [with a minimum radius of 40" (1 m)].

The straight line cutting and welding configuration consists of a carriage, master drive, racking group and control module. The optional MDS-1060-10 Cable Kit can be used to remote the control module.

A number of straight line control modules are available. The MDS-1002 Straight Line Module provides simple direction and speed control for continuous cutting or welding. The MDS-1003 Stitch Module provides a straight line and stitch welding mode with skip time, weld time and crater/puddle buildup time. The MDS-1004 Programmable Stitch Module provides digital display of all stitch welding parameters. The MDS-1004 Stitch Module has closed position feedback so all distances are set in inches or mm as opposed to time and are repeatable. The MDS-1055 Universal Limit Kit adds cycler, stop at limit and rapid return functions to the MDS-1002 and MDS-1003 modules. The MDS-1004 Programmable Module has built in stop at limit and rapid return modes. For more features, see the appropriate pages on each of the modules.

The Master Drive is rated at 60 lbs (27 kg) vertical load. (International Robotics Standards Rating)\*\* The machine is equipped with overload protection.

# STANDARD FEATURES:

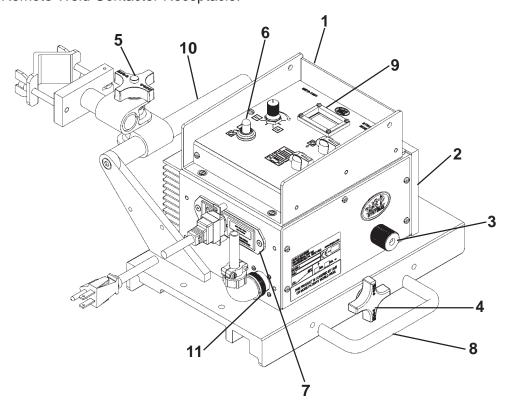
The Master Drive Unit incorporates the following standard internal features:

- High torque, low inertia motor for precise stops and starts.
- Dedicated fail-safe brake with three times the stopping and holding power of the motor.
- Motor overload protection which turns off the motor and engages the brake when excessive load is placed on the machine.
- Closed loop speed control for adjustable and repeatable control of critical welding or cutting parameters.
- Closed loop position control to prevent position creep when the machine stops to perform an operation such as crater fill at the end of a stitch weld.

<sup>\*\*</sup>The International Robotics Standards Rating requires a minimum of 2:1 continuous-duty safety margin on all power train and electronics components.

# **ADDITIONAL FEATURES:**

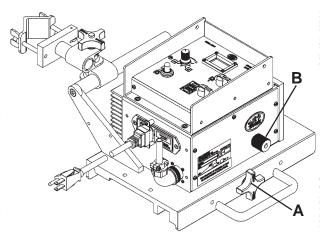
- 1. Control Module that is easily remoted or changed.
- 2. Master Power Drive Module that is reconfigurable by the user, for different applications, by adding or changing mating modules and accessories.
- **3.** Clutch, to enable rapid manual repositioning of the carriage anywhere on the track.
- **4.** Wheel engagement knob, which enables placement of the releasable carriage anywhere on the track.
- **5.** Optional cable mounting bar with anchor clamp to keep the welding cables and contact wires away from the work surface.
- 6. Contactor ON/OFF switch.
- **7.** Power Entry Box with:
  - a) Input Power Fuse
  - b) Machine ON/OFF Switch
  - c) Power Cord Mating Connector
- **8.** Standard Carrying Handle.
- **9.** Digital speed readout for more repeatable welding/cutting.
- 10. Optional Carrying Handle and Mounting Bar.
- 11. Remote Weld Contactor Receptacle.



# **SETUP**

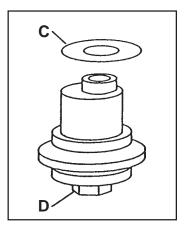
# 1) WHEEL ADJUSTMENT AND ALIGNMENT

Always check for proper carriage wheel adjustment before using the machine. Turn the wheel engagement knob (A) on the side of the carriage until the wheels are fully moved towards the center of the carriage (engaged). Then rotate the drive clutch knob (B) fully counter clockwise to disengage the drive pinion. Slide the carriage onto the end of a track. The wheels should slide into the track V-grooves and the carriage will move smoothly along the track if the wheels are properly aligned.



The wheels along one side of the carriage have stainless steel shim washers **(C)** underneath. These wheels are adjustable. Readjust these wheels (if necessary) by rotating the hex bolt **(D)** with a 1/2" wrench.

Grasp the sides of the carriage. The wheels are too loose if it is possible to move the carriage from side to side or up and down. Use a finger to keep one of the adjustable wheels from rotating as the carriage is manually pushed along the track. The wheels are adjusted too tight if firm finger pressure is not enough to prevent wheel rotation. Repeat the process for the other adjustable wheel.



# 2) POSITIONING THE MACHINE ON THE TRACK

Position the rail using magnet plates or vacuum cups. Wipe the track grooves free of weld splatter and other debris. This will prevent binding and premature rail and wheel wear. Lubricate the rack using a dry spray, if desired, for extended track life.

Turn the wheel engagement knob (A) on the side of the carriage fully counter clockwise to disengage the wheels. Then rotate the Master Drive clutch knob (B) fully counter clockwise to disengage the drive pinion. The carriage can now be placed anywhere on the track. Turn the wheel engagement knob (A) clockwise to engage the wheels firmly in the V-grooves. Verity all four wheels are in the grooves. Manually move the carriage along the track to verify the motion is smooth and the wheel alignment is correct. Rotate the Master Drive clutch knob (B) fully clockwise while gently rocking the machine forward and backward to fully engage the drive pinion. The rocking motion is necessary to help insure proper gear mesh.

# SETUP (CONT'D.)

# 3) REMOTE CONTACTOR WIRING

Connect the remote weld contactor to the welding source as shown below:

Pins A and B ...... connection for welder #1 Pins C and D ...... connection for welder #2

# 4) GUN AND TORCH SETUP

For welding, insert the welding gun into the all-position clamp on the rack. Adjust the clamp, the clamp block and the rack to position the gun for welding. Connect the weld contactor connector to the rear of the main drive unit. Route the welding cable and weld contactor wires through the cable anchor clamp.

For cutting, insert the cutting torch into the torchholder on the rack. Adjust the torchholder, the clamp block and the rack to position the torch for cutting. Connect the hose assembly to the manifold and the cutting torch. The manifold acts as a strain relief on the supply hoses as well as a quick shut-off valve for the gases. Once the torch valves are adjusted, the manifold eliminates the need for continuous adjustments and keeps the supply lines from dragging the torch out of position.

# 5) MACHINE OPERATION

Turn the main power ON at the power entry box. Set the following parameters on the control module in use:

#### STRAIGHT LINE MODULE

# STITCH MODULE

Machine Speed

Direction

Weld Contactor ON/OFF

Machine Mode

- a) Forward/Reverse
- \*b) Stop at limit in direction of travel
- \*c) Cycle between limits

\*The installation of the MDS-1055 Universal Limit Kit provides these modes.

Welding Speed

Direction

Weld Contactor ONIOFF

Welding Mode

- a) Stitch
- b) Continuous

Stitch Mode Controls

- a) Skip Time
- b) Weld Time
- c) Puddle Buildup and Crater Fill Time (occurs at the beginning and end of each weld)

CAUTION: The Speed Control Card in the Master Drive is NOT interchangeable with the speed card in the Linear or Pendulum Weavers.

# TECHNICAL DATA

#### MASTER DRIVE UNIT

## **Power Requirements:**

Part Number	<u>Voltage / Hz</u>	Fuse Size
MPD-1000	120 VAC/50-60 Hz	2A
MPD-1002	240 VAC/50-60 Hz	3A
MPD-1004	42 VAC/50-60 Hz	6A

**Dimensions:** 7.75" L x 6.00" W x 4.25" H

(197 x 152 x 108 mm)

Vertical - 60 lbs (27 kg) [International Robotics Standards Rating]\*\* Load Capacity:

Horizontal - 100 lbs (45 kg)

Speed Range: 2-120 in/min (51-3048 mm/min)

**Net Weight:** 10 lbs (4.5 kg)

Shipping Weight: 13 lbs (5.9 kg)

# MDS-1002 STRAIGHT LINE MODULE or MDS-1003 STITCH MODULE

7.50" L x 6.00" W x 2.00" H (191 x 152 x 51 mm) **Dimensions:** 

**Net Weight:** 1.75 lbs (0.8 kg)

Shipping Weight: 3.0 lbs (1.4 kg)

# **DIMENSIONS**

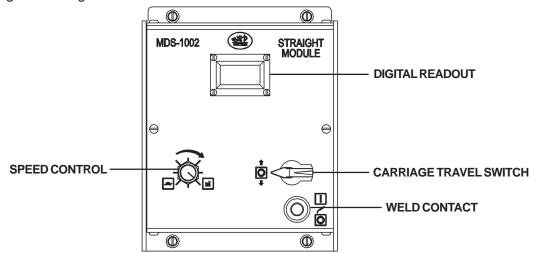
# 2.50" (64 mm) **Control Module** 6.00" (152 mm) **Master Drive** 0 MDS-1003 (191 mm) 0 7 7.13" (181 mm) 6.00" 7.75" (152 mm) (197 mm) 4.25" (108 mm)

7.50"

<sup>\*\*</sup>The Master Drive is rated at 60 lbs (27 kg) vertical load. The International Robotics Standards Rating requires a minimum of 2:1 continuous-duty safety margin on all power train and electronics components. The machine is equipped with overload protection.

# MDS-1002 STRAIGHT MODULE

The MDS-1002 Straight Module provides direction and speed control for continuous cutting or welding.



**SPEED CONTROL:** Sets the tractor speed from 2-120 in/min (5.1-304.8 cm/min).

CARRIAGE TRAVEL SWITCH: Provides FORWARD/STOP/REVERSE direction control.

**DIGITAL READOUT:** The display is dual function.

- a) PRESET SPEED Displayed when the CARRIAGE TRAVEL SWITCH is OFF or motion is halted by a motor overload condition.
- **b) MEASURED SPEED** Displayed when power is applied to the motor. (This will be the same as the Preset Speed.)

The readout is factory set to display the carriage speed in cm/min. The display can be rescaled, as required, or readjusted to read in/min by following the instructions found in the "**DIGITAL READOUT CALIBRATION**" section of this manual.

**WELD CONTACT:** Opens/closes a pair of independent 1 Amp contacts (pins A & B and C & D) at the weld contactor receptacle.

**NOTE:** A safety interlock will automatically open the weld contacts if the motor overload protection halts machine motion. Clear the overload by turning the carriage travel switch to off. Resetting the overload fault will not cause the contacts to automatically reclose. Use the weld contact switch to restart the welder after clearing the overload.

#### REPLACEMENT POTS AND SWITCHES

#### **CARRIAGE TRAVEL:**

Switch and Spacer	MDS-1112
Black Pointer Knob	BUG-9694

#### SPEED CONTROL:

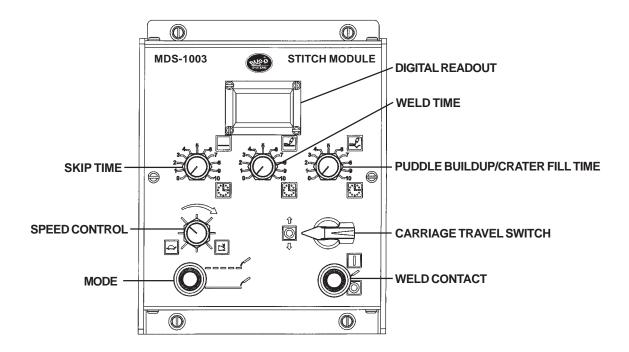
PCB-1026
MDS-1018
MDS-1046

#### **WELD CONTACT:**

Switch and Spacer	MDS-1115
Toggle Switch Boot	MDS-1047

# MDS-1003 STITCH MODULE

The MDS-1003 Stitch Module provides direction and speed control for continuous welding and cutting. In addition, a stitch welding mode is provided, with adjustments for skip time (welder off), weld on time and puddle buildup/crater fill time.



**SPEED CONTROL:** Sets the tractor weld speed from 2-120 in/min (5.1-304.8 cm/min).

CARRIAGE TRAVEL SWITCH: Provides FORWARD/STOP/REVERSE direction control.

**DIGITAL READOUT:** The display is dual function.

- a) PRESET SPEED Displayed when the CARRIAGE TRAVEL SWITCH is OFF or motion is halted by a motor overload condition.
- **b) MEASURED SPEED -** Displayed when power is applied to the motor. (This will be the same as the Preset Speed.)

The readout is factory set to display the carriage speed in cm/min. The display can be rescaled, as required, or readjusted to read in/min by following the instructions found in the "**DIGITAL READ-OUT CALIBRATION**" section of this manual.

**WELD CONTACT:** Opens/closes a pair of independent 1 Amp contacts (pins A & B and C & D) at the weld contactor receptacle. In STITCH mode, this switch acts as a weld contact enable and the stitch module cycles the contacts on and off.

**NOTE:** A safety interlock will automatically open the weld contacts if the motor overload protection halts machine motion. Clear the overload by turning the carriage travel switch to off. Resetting the overload fault will not cause the contacts to automatically reclose. Use the weld contact switch to restart the welder after clearing the overload.

# MDS-1003 STITCH MODULE (CONT'D.)

STITCH/CONTINUOUS: Selects between cyclic (Stitch) welding and continuous welding or cutting.

- a) CONTINUOUS Selects continuous welding or cutting.
- b) STITCH Selects the cyclic (Stitch) welding mode. This mode consists of four continuously repeated steps.
  - The machine stops moving for the selected time to perform Puddle Buildup.
  - 2) The machine welds at the selected welding speed for the time selected using the **Weld Time** control.
  - 3) The machine stops moving for the selected time to perform Crater Fill.
  - 4) The machine turns off the welder and moves at maximum speed to where the next weld needs performed. This location is determined by setting a Skip Time control.

**WELD TIME:** This control functions only when the mode switch is set to **Stitch**. Weld time sets a weld length time from 1-50 seconds. This corresponds to a weld length of approximately 0.03-100 inches (0.8-2540 mm). **NOTE:** The operator must manually enable the weld contactor by turning on the **Weld Contact** or the welder will never cycle on and off.

**SKIP TIME:** This control functions only when the mode switch is set to **Stitch**. Skip time sets how long the machine travels between welds (0.3-15 seconds). This corresponds with a skip length of approximately 0.6-30 inches (15-760 mm). The machine always moves between welds at maximum speed.

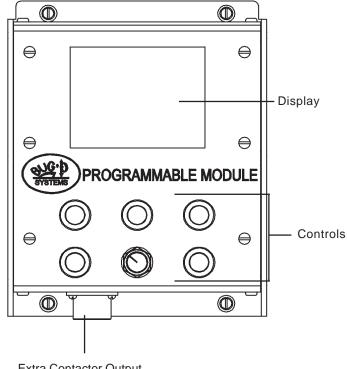
**PUDDLE BUILDUP / CRATER FILL TIME:** This control functions only when the mode switch is set to **Stitch**. Puddle Buildup/Crater Fill Time sets the time the machine is stopped at the beginning and end of every weld (0-1.5 sec).

#### REPLACEMENT POTS AND SWITCHES

WELD COM	NTACT: Switch and Spacer Toggle Switch Boot	MDS-1116 MDS-1047	CARRIAGE TRAVEL SWITCH: Switch and Spacer MDS-1112 Black Pointer Knob BUG-9694
PUDDLE B	SUILDUP/CRATER FILL TI 500K Ω Pot, 3/4 turn Black Knob Knob Seal Nut	ME: MDS-1053 MDS-1018 MDS-1046	WELD TIME: 500K $\Omega$ Pot, 3/4 turn MDS-1053 Black Knob MDS-1018 Knob Seal Nut MDS-1046
SKIP TIME	: 500K Ω Pot, 3/4 turn Black Knob Knob Seal Nut	MDS-1053 MDS-1018 MDS-1046	SPEED CONTROL:  10K Ω Pot, 3 turn Black Knob Shaft Seal Nut  PCB-1026 MDS-1018 MDS-1046
MODE:	Switch and Spacer Toggle Switch Boot	MDS-1115 MDS-1047	

# MDS-1004 PROGRAMMABLE MODULE

The MDS-1004 PROGRAMMABLE MODULE provides stitch controls for welding or cutting with the Modular Drive System. All stitching parameters are set and displayed on a graphic screen. This allows each setting to be set exactly the same every time.

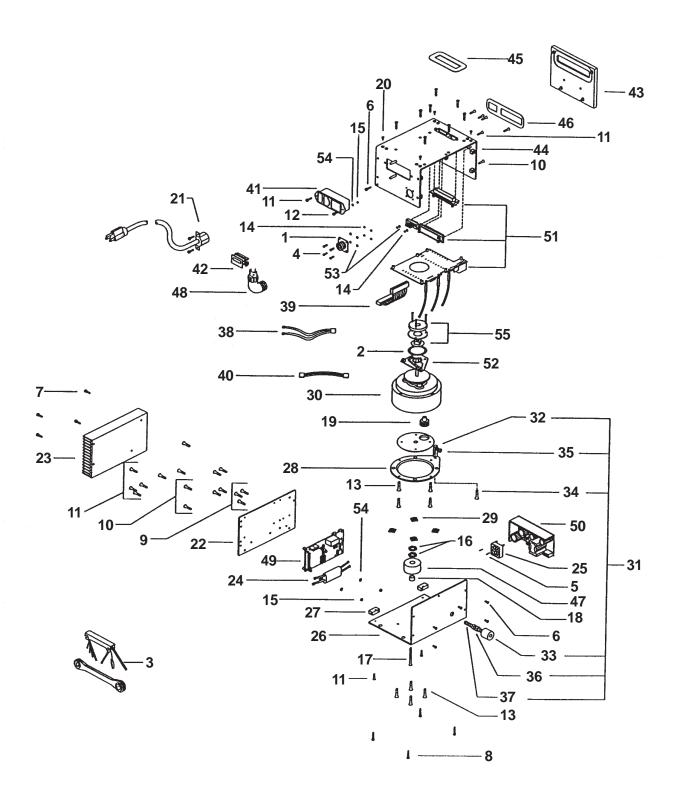


Extra Contactor Output

#### **FEATURES**

- Each stitch setting is displayed while being set. This allows each setting to be exactly set each time a job is set up.
- Closed loop encoder feedback is employed to ensure the traveled distances match the set distances.
- The module provides an extra contactor output. This output and the output on the Modular Drive can be disabled or enabled independently.
- The module will stop the machine or return it to start after a preset number of welds. This eliminates the need for external limit switches.
- This unit can return past the start location to allow for work piece changes. One button will start the whole welding procedure.
- Stitch welds stopped in mid-job can be restarted without interrupting the weld pattern.
- Puddle-buildup and Crater-fill timers are independent.

# MPD-1000 MASTER DRIVE UNIT / EXPLODED VIEW

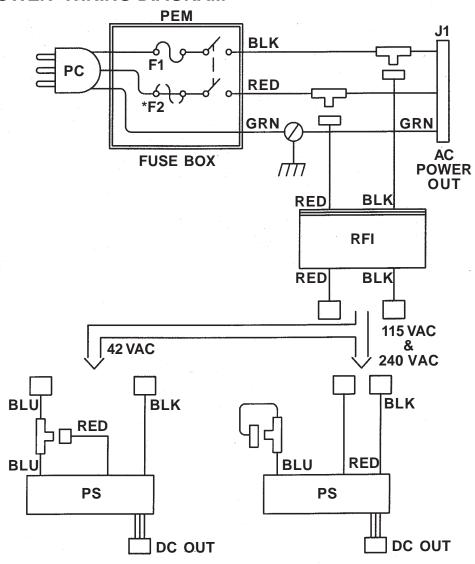


# MPD-1000 MASTER DRIVE UNIT / PARTS LIST

<b>ITEM</b>	<b>QTY</b>	PART NUMBER	DESCRIPTION
1	1	BUG-1034	Panel Connector, 4-T, Male
2	1	WPD-1013	Rubber Ring Gasket
3	1	BUG-9444	Tool Kit
4	4	FAS-0104	Pan Hd Screw 4-40 x 318 Lg
5	2	FAS-0107	Pan Hd Screw 4-40 x 3/4 Lg
6	6	FAS-0114	Pan Hd Screw 6-32 x 3/8 Lg
7	4	FAS-0504	Soc Hd Cap Scr 4-40 x 3/8 Lg
8	4	FAS-0557	Soc Hd Cap Scr 1/4-20 x 3/4 Lg
9	3	FAS-0902	Fit Hd Soc Scr 4-40 x 1/4 Lg
10	19	FAS-0905	Fit Hd Soc Scr 4-40 x 1/2 Lg
11	11	FAS-0914	Fit Hd Soc Scr 6-32 x 3/8 Lg
12	1	FAS-0915	Fit Hd Soc Scr 6-32 x 1/2 Lg
13	8	FAS-0923	Fit Hd Soc Scr 8-32 x 5/16 Lg
14	6	FAS- 1305	Hex Nut 4-40
15 16	3	FAS- 1310	Hex Nut 6-32
16 17	2	FAS-1325	Hex Nut 8-32 Nylon  Fit Hd Sit Sor 8-32 v 1 1/2 La
17 18	1 1	FAS-2823 GOF-3012	Fit Hd Sit Scr 8-32 x 1 1/2 Lg Spacer 1/2 OD x 5/16 Lg
19	1	GOF-3012 GOF-3014	Pinion
20	4	MDS-1019	Snap Rivet, Black
*21	1	MPD-1001	Power Cord 120 VAC
22	i	MPD-1006	Side Panel
23	i	MPD-1007	Heat Sink
24	i	MPD-1008	Filter
25	1	MPD-1009	Fan Assembly
26	i	MPD-1011	Base Panel
27	2	MPD-1012	Mounting Block
28	1	MPD-1090	Matched Clutch Plts
**29	1	BUG-2593	Glide Flat
30	1	MPD-1015	Gear Motor (60:1)
31	1	MPD-1016	Clutch Assembly (Includes items 32 through 37)
32	1	BUG-1216	Ball Joint
33	1	BUG-1857	Knob
34	1	FAS-0945	Fit Hd Soc Scr 10-32 x 1/2 Lg
35	1	FAS-1341	Hex Jam Nut 10-32
36	2	FAS-1390	Hex Nut 3/8-16
37	1	MPD-1017	3/8-16 Threaded Stud
38	1	MPD-1018	Wiring Harness-Speed Board to Motor
39	1	MPD-1019	Wiring Harness-Interconnect to Speed Bd/Control
40	1	MPD-1020	Wiring Harness-Interconnect to Speed Bd/Power
41 *42	1	MPD-1025	Power Entry Module
	1 1	MPD-1026	Fuse 2A
43 44	1	MPD-1029 MPD-1031	Connector Cover Plate
44 45	1	MPD-1031 MPD-1038	Cover Panel (Includes item # 20) Gasket for 50-Pin Connector
46	1	MPD-1036	Gasket for 50-Pin/3-Pin Connector
47	1	MPD-1042	Inductor, Potted-with Connectors
48	i	MUG-1617	Cable Connector, 4-T, Female, Elbow
49	i	PCB-1000	Speed Board
*50	i	PCB-1005-120	Power Supply Assembly 165W 120 VAC
51	1	PGB-1010	Interconnect Board
52	1	PCB-1012	Position Card
53	6	WAS-0201	# 4 Internal Star Lockwasher
54	3	WAS-0211	# 6 Internal Star Lockwasher
55	1	WPD-1012	Brake Assembly
			•

<sup>\*</sup> See Electrical Component Chart for 240 VAC and 42 VAC Part Numbers \*\*Included in Item 28.

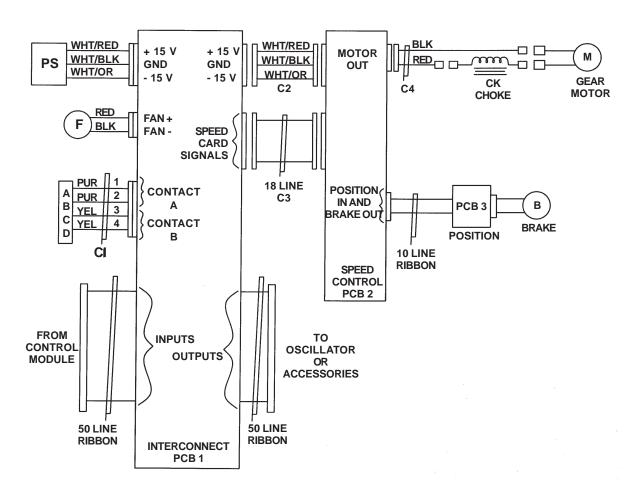
# **AC POWER WIRING DIAGRAM**



# **ELECTRICAL COMPONENT CHART**

		PART NUMBER		
ITEM	DESCRIPTION	MPD-1000 120 VAC	MPD-1002 240 VAC	MPD-1004 42 VAC
F1,F2*	Fuses	(1) MPD-1026 2A	(2) MPD-1027 3A	(2) MPD-1067 6A
PC	Power Cord	MPD-1001	MPD-1003	MPD-1005
PS	Power Supply	PCB-1005-120	PCB-1005-240	PCB-1005-42
J1	Connector w/Pins		MPD-1021	
PEM	Power Entry Module		MPD-1025	
RFI	Filter Module		MPD-1008	
*F2 replaced with bus wire on 120 VAC				

# **SIGNAL WIRING**



# **PARTS LIST**

ITEM	DESCRIPTION	PART NUMBER
В	Brake Assembly	WPD-1012
CI	Contactor Cable Assembly	MPD-1036
C2	DC Power Cable Assembly	MPD-1020
C3	Speed Card Cable Assembly	MPD-1019
C4	Motor Wiring	MPD-1018
CK	Inductor Pot Assembly (Choke)	MPD-1042
F	Fan Assembly	MPD-1009
М	Gear Motor	MPD-1015
PCB1	Interconnect Card	PCB-1010
PCB2	Tractor Speed Card	PCB-1000
PCB3	Position Sensor Card	PCB-1012
PS	Power Supply	(see AC Wiring Diagram)

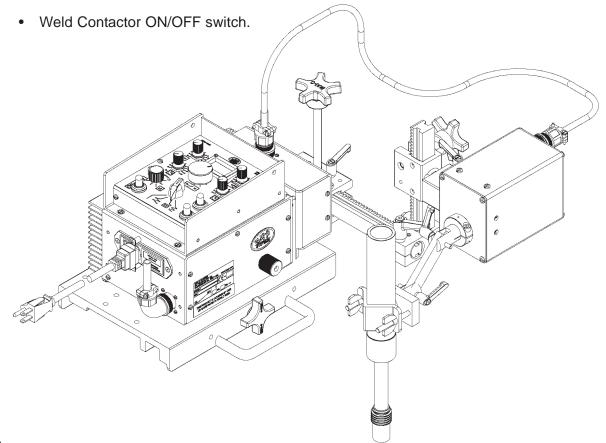
# WPD-2100 PENDULUM WEAVER II

# INTRODUCTION

The **Pendulum Weaver** and **Weaver Control Module** add a pendulum-type weaving motion to the Modular Drive System. The Pendulum Weaver is particularly useful for weaving fillet welds in a corner joint. The weaver motor box is mounted to the front of the carriage using standard racks and rackholders.

# **FEATURES**

- High torque, low inertia motor for precise starts and stops.
- Heavy duty planetary gear box with powerful output shaft for rotating welding gun and attachments for the gun.
- High speed pendulum motion with independent control of right and left dwell times.
- High motor gearing ratio, that prevents the welding gun from moving by backdriving the gear train when power is off.
- Closed loop speed control for adjustable and repeatable control of critical welding or cutting parameters.
- Closed loop position control to prevent drift from the center position.
- Gun mounting group with adjustable racking block for accurate positioning of the gun.



# PENDULUM WEAVER II SETUP

# INSTALLATION

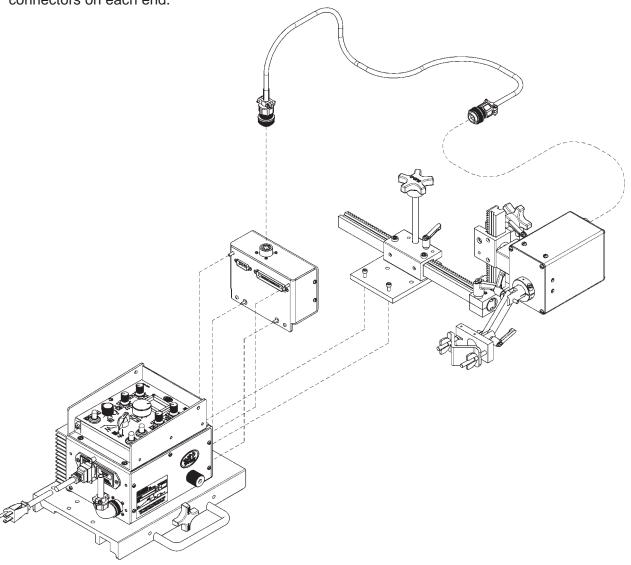
The Weaver Control Module plugs into the Master Drive Unit. Use a flat blade screwdriver to firmly secure the four corners of the module.

Plug the Pendulum Weaver Electronics box into the front end of the Master Drive Unit. Secure the box to the drive unit by using the four captive screws on the electronics box.

Bolt the mounting plate onto the front of the carriage, below the electronics box, and bolt the rackholder onto the mounting plate. Insert the 14" (355 mm) rack through it.

Several different arrangements can be used to mount the gearbox on the rack and to position the welding gun. One recommended assembly method is shown below: bolt the racks, gearbox, and clamps together as shown in the diagram.

Finally connect the gearbox to the electronics box using the cable supplied, with 6-pin connectors on each end.



# SETUP AND ALIGNMENT

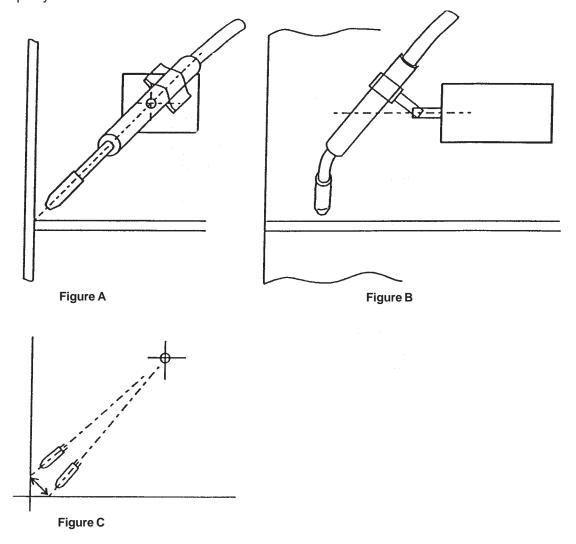
Attach the rail parallel to the weld joint, with magnet bars or vacuum cups. Position the drive carriage on the rail - see Modular Drive instructions if necessary.

Insert the welding gun into the clamp on the pendulum weaver. Adjust the racks and clamps to align the welding gun tip with the weld joint, and tighten firmly in place.

#### **IMPORTANT!**

When the welding gun is clamped in place with the nozzle pointing into the weld groove, the centerline of the wire must pass through the axis of the gearbox output shaft, as shown in Figure A, which is a view looking along the shaft. Figure B shows the side view of the same.

For a fillet weld, the nozzle will be at a 45° angle as shown in Figure C, and will swing equally in both directions.



**CAUTION:** The Speed Control Card in the Pendulum Weaver is NOT interchangeable with the speed card in the Master Drive or Linear Weaver.

# TECHNICAL DATA

# WPD-2100 PENDULUM WEAVER II

Power Uses 70 watts,

**Requirements:** received from Master Drive Unit.

**Dimensions:** 

**Electronics Box:** 6.0"W x 4.38"H x 2.38"L (152 x 111 x 60.3 mm)

**Gearbox:** 3.31"W x 4.10"H x 5.66"L (84 x 104 x 144 mm)

**Net Weight:** 12.88 lbs (5.84 kg)

**Speed:**\* 0 - 200 ipm (0-5100 mm/m)

Cycles:\* 3.7 cycles per second at 1/8" (3 mm) stroke

3.0 cycles per second at 1/4"(6 mm) stroke 2.0 cycles per second at 1/2" (12 mm) stroke 1.3 cycles per second at 1.0"(25 mm) stroke

(at maximum speed and 0 dwell)

**Stroke:**\* 2"(50 mm)

Steering:\* 4"(100 mm) to 2" (50 mm), each side of center

**Dwell Time:** 0 - 3 seconds, left and right

Load Capacity: 10 lbs (4.5 kg)

\*all measured at a 6" radius

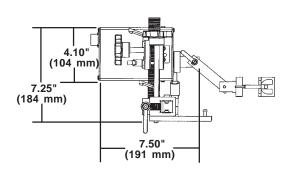
# **DIMENSIONS**

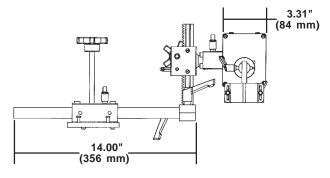




# 19.00" (483 mm) 5.66" (144 mm)

# **Electronics Box**





# **WPD-1100 LINEAR WEAVER**

# INTRODUCTION

The **Linear Weaver** and **Weaver Control Module** add weave welding capability to the Modular Drive System. The Linear Weaver bolts onto the front of the carriage and the Weaver Control Module plugs into the top of the Master Drive Unit. The optional MDS-1020 Cable Kit can be used to remote the Control Module.

#### **FEATURES**

The Linear Weaver and Weaver Control Module incorporate the following standard features:

- High torque, low inertia motor for precise stops and starts.
- High speed Linear Weaver for weaving, with independent control of right and left dwell times.
- High motor gearing which prevents the crossarm from moving when the unit is turned off.
- Closed loop speed control for adjustable and repeatable control of critical welding or cutting parameters.
- Closed loop position control to prevent drift from the center weld position.
- Clutch, to enable rapid installation or replacement of the weaver cross arm.
- Gun mounting group with adjustable racking block for accurate positioning of the gun.
- Contactor ON/OFF switch.

The figure below shows how the Linear Weaver and Weaver Control Module connect to the carriage and Master Drive Unit.

LINEAR WEAVER CROSS ARM

WEAVER CONTROL MODULE

WEAVER CLUTCH (KNOB ADJUSTMENT)

CARRIAGE

MASTER DRIVE UNIT

#### LINEAR WEAVER SETUP

# 1) WEAVER CONTROL MODULE AND LINEAR WEAVER INSTALLATION

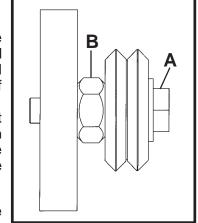
The Weaver Control Module plugs into the top of the Master Drive Unit. Use a flat head screw driver to firmly secure the four corners of the module.

Place the Linear Weaver on a flat surface, connector side up. Loosen the bolts that hold the Master Drive Module to the carriage. Plug the Master Drive Module into the Linear Weaver. The connectors should fit together easily and do not need forced. Attach the Linear Weaver to the carriage using the two weaver mounting bolts. **DO NOT SUBSTITUTE LONGER BOLTS.** Retighten the bolts that hold the Master Drive Unit to the carriage.

# 2) CROSSARM WHEEL ADJUSTMENT AND ALIGNMENT

Always check the crossarm wheel adjustment before using the machine. The wheels are too loose and need adjustment if the crossarm can move up and down. Normal gear backlash will permit crossarm side to side movement of approximately 0.02" (0.5 mm).

If the wheels need adjustment, remove the left and right weaver end covers. The two top wheels are adjustable. Loosen the hex bolt (A) until the adjustable bushing (B) can be rotated. Correct the wheel alignment by rotating adjustable bushing (B).



Check for proper alignment by using a finger to keep one of the wheels from rotating while manually moving the

crossarm. The wheels are adjusted too tight if firm finger pressure is not enough to prevent wheel rotation. Once aligned, hold the adjustment bushing **(B)** still while tightening the hex bolt **(A)**. Recheck alignment.

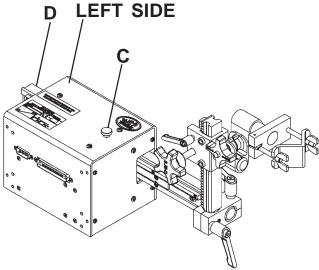
# 3) REALIGNING THE CROSSARM

(includes crossarm INSTALLATION and REMOVAL)

Rotate the clutch knob **(C)** fully counterclockwise. This disengages the drive pinion from the rack. Remove the two socket head screws from the crossarm **(D)**. The crossarm may be removed from or installed into the Linear Weaver at this time.

Turn on the AC power. Rotate the four-turn steering control knob and the weave speed knob on the Weaver Control Module fully clockwise. Turn the start/stop switch to START. Set the mode selector switch to NO WEAVE. Align the crossarm (**D**) so that 1 7/8" (48 mm) of the crossarm protrudes from the left side of the Linear Weaver. To insure proper gear mesh, gently rock the crossarm back and forth about 1/16" (2 mm) while engaging the pinion using the clutch knob (**C**).





CAUTION: IMPROPER GEAR MESH MAY CAUSE PINION, RACK, OR LINEAR WEAVER DAMAGE.

Set the weave amplitude to maximum. Use the steering knob on the control module to move the crossarm to both the extreme left and the extreme right. Perform measurements to determine if The crossarm is installed too far left or too far right. Repeat the crossarm realigning procedure changing the 1 7/8" (48 mm) dimension as required. Reinstall the two crossarm screws.

# LINEAR WEAVER SETUP (CONT'D.)

# 4) REMOTE CONTACTOR WIRING

Connect the remote weld contactor on the Master Drive to the welding source as shown below.

Pins A and B ......connection for welder #1
Pins C and D .....connection for welder #2

## 5) GUN AND SETUP

For welding, insert the welding gun into the all-position clamp on the rack. Adjust the clamp, the clamp block and the rack to position the gun for welding. Connect the weld contactor connector to the rear of the Master Drive Unit. Route the welding cable and weld contactor wires through the cable anchor clamp. Turn on the AC power. Use the steering knob on the control module to move the crossarm to both the extreme left and then the extreme right. Turn on the oscillator, at the same time, with the controls set to maximum weave width. Readjust the crossarm or the gun if the racking fixture hits the case during operation.

# 6) MACHINE OPERATION

Turn the main power ON at the power entry box. Set the following parameters using the control module:

Weld Mode Selector Switch

Tractor Travel Speed

Steering

Weave Amplitude

Weave speed

Left and Right Dwells

The Start/Stop control will turn on the weaver. To start welding, push the weld contactor switch "ON" (momentarily) which will turn on the wire feeder/weld current. Use the carriage travel switch to select a forward or reverse carriage travel direction.

**CAUTION:** The Speed Control Card in the Linear Weaver is **NOT** interchangeable with the speed card in the Master Drive or Pendulum Weaver.

# TECHNICAL DATA

## **WPD-1100 LINEAR WEAVER**

**Power** Receives power from Master Drive.

**Requirements:** Uses 70 additional watts.

**Dimensions:** 7.25" L x 5.50" W x 5.37" H (184 x 140 x 137 mm)

**Net Weight:** 13.5 lbs (6.0 kg)

Shipping Weight: 16.5 lbs (7.5 kg)

**Speed:** 2-110 in/min (51-2800 mm/min)

Cycles: 2.5 cycles per second at 1/8" (3mm) stroke

1.6 cycles per second at 1/4" (6mm) stroke 1.0 cycles per second at 1/2" (12mm) stroke 0.7 cycles per second at 1.0" (25mm) stroke

(at maximum speed and 0 dwell)

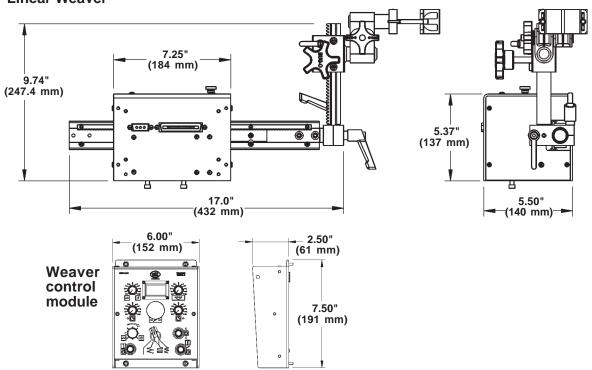
**Load Capacity:** 10 lbs (4.5 kg)

# MDS-1005 WEAVER CONTROL MODULE

**Dimensions:** 7.50" L x 6.00" W x 2.00" H (191 x 152 x 51 mm)

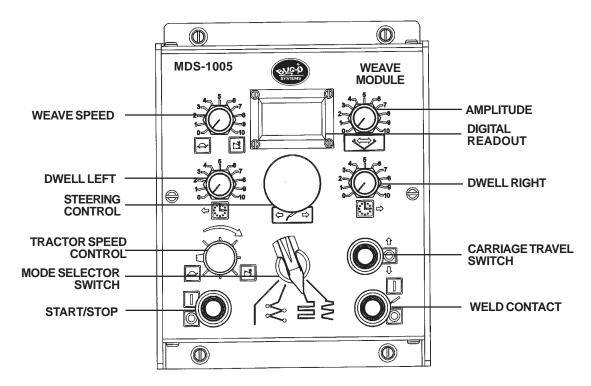
Net Weight: 1.75 lbs (0.8 kg) Shipping Weight: 3.0 lbs (1.4 kg)

## DIMENSIONS Linear Weaver



# MDS-1005 WEAVER CONTROL MODULE

The MDS-1005 Weaver Control Module provides weave welding control functions.



**AMPLITUDE (WEAVE):** Continuously adjustable up to a 2" (50 mm) maximum weaver stroke.

CARRIAGE TRAVEL SWITCH: Provides FORWARD/STOP/REVERSE direction control.

**DIGITAL READOUT:** Three tractor display modes exist.

- a) PRESET SPEED Displayed when the CARRIAGE TRAVEL SWITCH is OFF or motion is halted by a motor overload condition.
- b) CONTINUOUSLY MEASURED SPEED Displayed when the MODE SELECTOR SWITCH setting is RUN or NO WEAVE. (This will be the same as the Preset Speed.)
- c) SAMPLED SPEED The tractor motion alternates between moving at the Preset Speed and stopping when the MODE SELECTOR SWITCH is set to STEP or STOP ON DWELL. This is referred to as "stepping" the tractor. To avoid having the display continuously fluctuate between the zero speed and the actual speed, the readout measures the travel speed near the end of each tractor step. This speed is then displayed until another sample is taken at the end of the next tractor step. This provides a stable display of the measured travel speed. (This will be the same as the Preset Speed.)

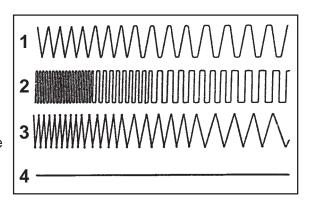
The readout is factory set to display the carriage speed in cm/min. The display can be rescaled, as required, or readjusted to read in/min by following the instructions found in the "**DIGITAL READOUT CALIBRATION**" section of this manual.

**LEFT AND RIGHT DWELL:** The left and right dwell controls have a 0-3 second adjustment range.

# MDS-1005 WEAVER CONTROL MODULE (CONT'D.)

**MODE SELECTOR SWITCH:** Four welding modes are available.

- RUN In this mode, power to the drive unit is always on and the machine travels continuously both during weave and dwell. Weave speed and dwell time both affect the weave pattern.
- 2) STEP The unit travels only during dwell and stops during the weaver cross stroke. Changing weave speed does not effect the weld pattern-dwell time does.
- TRACTOR STOP ON DWELL The tractor travels during the weave stroke; the tractor and weaver stop during dwell.
- 4) NO WEAVE In this mode oscillation is stopped. Only the tractor is powered. This mode is used for stringer passes.



**SPEED CONTROL (TRACTOR):** Sets the tractor speed from 2-120 in/min (5.1-304.8 cm/min).

**START/STOP:** This enables/disables all tractor and weaver motion.

**STEERING:** The three-turn steering knob has a +/- 2" (100 mm) range.

**WEAVE SPEED CONTROL:** Sets the weave speed from 0-100 in/min (0-254 cm/min).

**WELD CONTACT:** Opens/closes a pair of independent 1 Amp contacts (pins A & B and C & D) at the weld contactor receptacle.

**NOTE:** A safety interlock will automatically open the weld contacts if the motor overload protection halts machine motion. Clear the overload by turning the carriage travel switch to off. Resetting the overload fault will not cause the contacts to automatically reclose. Use the weld contact switch to restart the welder after clearing the overload.

#### REPLACEMENT POTS AND SWITCHES

# WELD CONTACT:

Switch and Spacer	MDS-1114
Toggle Switch Boot	MDS-1047

#### CARRIAGE TRAVEL SWITCH:

Switch and Spacer	MDS-1117
Toggle Switch Boot	MDS-1047

# DWELL RIGHT:

500K $\Omega$ Pot, 3/4 turn	MDS-1053
Black Knob	MDS-1018
Knob Seal Nut	MDS-1046

#### AMPLITUDE:

10K $\Omega$ Pot, 3/4 turn	MDS-1052
Black Knob	MDS-1018
Knob Seal Nut	MDS-1046

# MDS-1005 WEAVER CONTROL MODULE (CONT'D.)

# **WEAVE SPEED:**

 $10K \Omega$  Pot, 3/4 turnMDS-1052Black KnobMDS-1018Knob Seal NutMDS-1046

## STEERING CONTROL:

 $10K \Omega$  Pot, 3 turnPCB-1027Black KnobBUG-5757Knob Seal NutBUG-5759

# **DWELL LEFT**:

500K  $\Omega$  Pot, 3/4 turn MDS-1053 Black Knob MDS-1018 Knob Seal Nut MDS-1046

#### TRACTOR SPEED CONTROL:

10K  $\Omega$  Pot, 3/4 turnPCB-1024KnobMDS-1044Shaft Seal NutBUG-5759

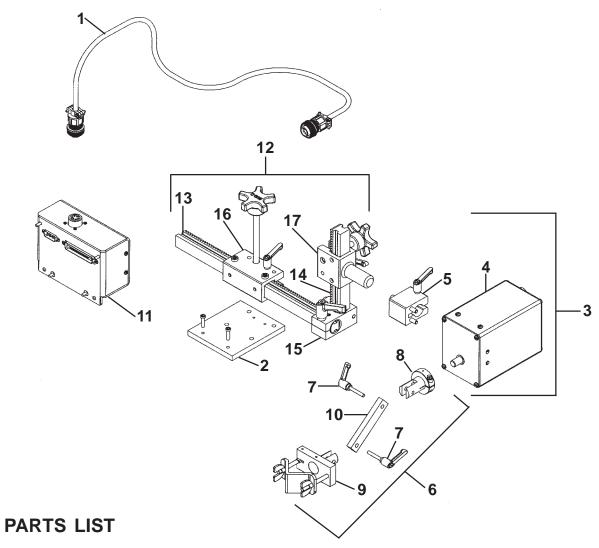
# MODE SELECTOR SWITCH:

Switch and Spacer MDS-1113 Black Pointer Knob BUG-9694

#### START/STOP:

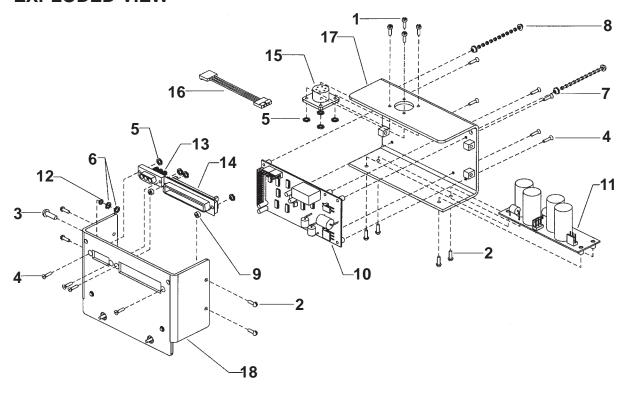
Switch and Spacer MDS-1115 Toggle Switch Boot MDS-1047

# WPD-2100 PENDULUM WEAVER II / EXPLODED VIEW / PARTS LIST



<u>ITEM</u> 1	<u>QTY</u> 1	<u>PART NO.</u> MUG-1634-3	<u>DESCRIPTION</u> Power Cable, 3'
2	1	MDS-1029	Mounting Plate w/Screws
3	1	WPD-2110	Pendulum Gear Box (Includes items 4, 5, 6,)
4	1	WPD-2115	Gear Box
5	1	WPD-2041	Clamp Block
6	1	WPD-2050	Gun Mounting Group (Includes items 7 thru 10)
7	2	BUG-2234	Adjustable Clamping Lever
8	1	WPD-2044	Shaft Adaptor w/Collar
9	1	WPD-2052	Gun Clamp
10	1	WPD-2053	Link
11	1	WPD-2120	Pendulum Weaver Electronics Box
12	1	WPD-2040	Pendulum Mounting Group (Includes items 13 thru 17)
13	1	BUG-1796	Machined Rack 14"
14	1	BUG-1853	Machined Rack 7-1/2"
15	1	BUG-5462	Right Angle Clamp
16	1	MDS-1031	3.5" Rackholder w/Long Handle
17	1	UNI-1036	Rackrider w/Post

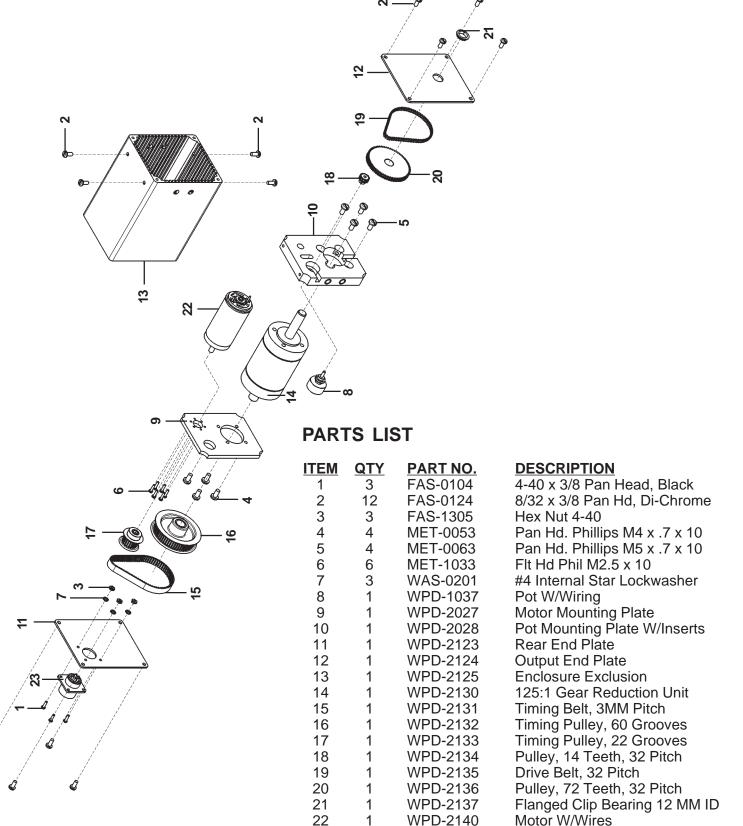
# WPD-2120 PENDULUM WEAVER II ELECTRONICS / EXPLODED VIEW



# **PARTS LIST**

<b>ITEM</b>	QTY	PART NO.	DESCRIPTION
1	4	FAS-0104	Pan Hd Scr 4-40 x 3/8 Lg
2	8	FAS-0114	Pan Hd Scr 6-32 x 3/8 Lg
3	1	FAS-0225	Rnd Hd Scr 8-32 x 1/2 Lg
4	10	FAS-0905	Flt Hd Soc Scr 4-40 x 1/2 Lg
5	8	FAS-1305	Hex Nut 4-40
6	2	FAS-1320	Hex Nut 8-32
7	2	FAS-1322	Hex Nut 8-32 Nylock
8	2	FAS-2127	Pan Hd Scr 8-32 x 2 3/4 Lg
9	2	MDS-1034	Spacer Washer .125 ID x .255 OD x .06 Thick
10	1	PCB-1009	Speed Board for Pendulum Weaver
11	1	PCB-1021	Capacitor Card
12	1	WAS-0221	#8 Internal Star Lockwasher
13	1	WPD-1001	Ground Harness
14	1	WPD-1023	Connector, 50-Pin, Male
15	1	WPD-2005	Wiring Harness
16	1	WPD-2006	Wiring Harness-Capacitor Bd to Speed Bd
17	1	WPD-2011	Front Panel
18	1	WPD-2012	Rear Panel

# WPD-2115 PENDULUM GEAR BOX / EXPLODED VIEW



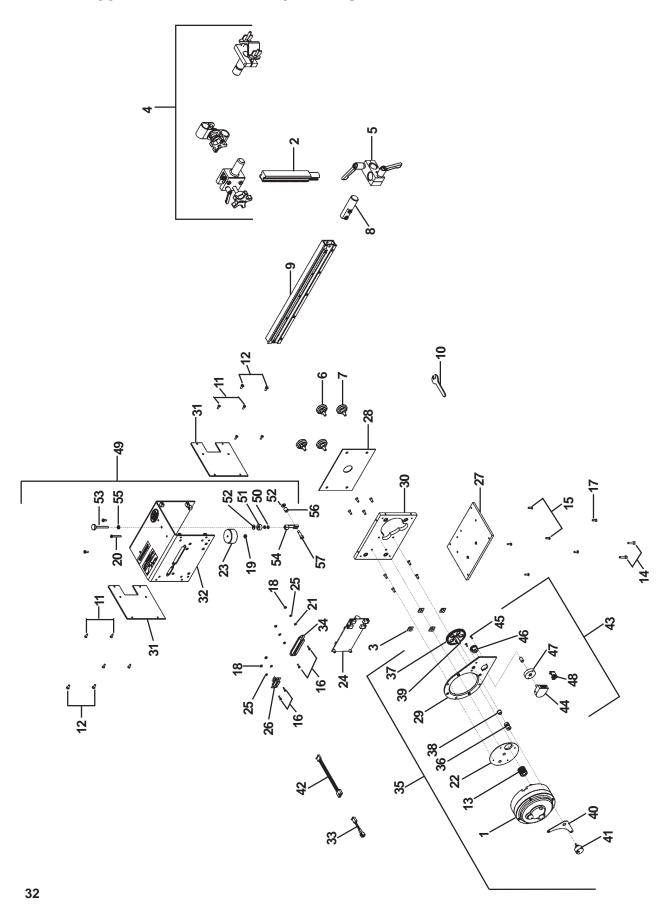
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WPD-2141

Wiring Harness

# WPD-1100 LINEAR WEAVER / EXPLODED VIEW



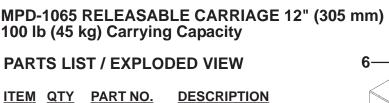
# WPD-1100 LINEAR WEAVER / PARTS LIST

ITEM	QTY	PART NO.	DESCRIPTION
1	1	BUG-1590	Gear Motor (80:1)
2	1	BUG-1853	Machine Rack 7 1/2" Lg
3	4	BUG-2593	Glide Flat
4	1	BUG-5455	Gun Mounting Group
5	1	BUG-5462	Right Angle Clamp
6 7	2 2	CWO-4021	Adj Leg & Wheel Assembly
8	1	CWO-4020 WPD-1178	Fixed Leg & Wheel Assembly Post w/Fasteners
9	1	WPD-1150	Cross Arm
10	i	BUG-9447	Wrench
11	8	FAS-0114	Pan Hd Scr 6-32 x 3/8 Lg
12	6	FAS-0124	Pan Hd Scr 8-32 x 3/8 Lg
13	1	WPD-1028	Pinion, 3/4 PD, 24 Teeth
14	2	FAS-0557	Soc Hd Cap Scr 1/4-20 x 3/4 Lg
15 16	4	FAS-0815	Fit Hd Sit Scr 6-32 x 1/2 Lg
16 17	10 10	FAS-0905 FAS-0925	FIt Hd Soc Scr 4-40 x 1/2 Lg FIt Hd Soc Scr 8-32 x 1/2 Lg
18	4	FAS-1305	Hex Nut 4-40
19	i	FAS-1325	Hex Nut 8-32 Nylon
20	1	FAS-2121	Pan Hd Scr 8-32 x 1 1/4 Lg
21	2	MDS-1034	Spacer Washer .125 ID x .255 OD x .06 Thk
22	1	MPD-1013	Clutch Plate
23	1	MPD-1042	Inductor, Potted w/Connectors
24	1	PCB-1001	Speed Board for DC 20
25 26	4 1	WAS-0201 WPD-1001	# 4 Internal Star Lockwasher Ground Harness
27	1	WPD-1001	Weaver Base Plate
28	i	WPD-1103	Dust Plate
29	1	WPD-1004	Motor Mount Plate
30	1	WPD-1106	Oscillator Mount Plate
31	2	WPD-1110	Side Panel
32	1	WPD-1020	Cover Panel
33 34	1 1	WPD-1022	Wiring Harness-Speed Board to Motor
3 <del>4</del> 35	1	WPD-1023 WPD-1025	Connector, 50-Pin, M Pot/Gear Assembly (Includes items 36 thru 41)
36	1	BUG-5235	Flexible Coupling
37	1	BUG-5596	Gear, 72 Teeth
38	1	BFX-1 218	Flange Bearing
39	1	WPD-1026	Shaft .250 Dia x .675 Lg
40	1	WPD-1027	Pot Mounting Bracket
41	1	WPD-1037	Potentiometer w/Wiring
42 43	1 1	WPD-1029 WPD-1030	Encoder/Speed Board Wiring Harness Pinion/Encoder Assembly (Includes items 44 thru 48)
44	1	BUG-6039	Encoder
45	2	FAS-0904	Flt Hd Soc Scr 4-40 x 3/8 Lg
46	1	WPD-1031	Pinion Assembly
47	1	WPD-1033	Encoder Spacer
48	1	WPD-1034	Encoder Card
49 50	1	WPD-1035	Clutch Assembly (Includes items 50 thru 55)
50 51	2	FAS-1340	Hex Nut 10-32
51 52	1 2	SFX-1224 WAS-0230	Sleeve #10 Washer
53	1	WPD-1038	Thumb Screw Knob with 1.75" Stud
54	1	WPD-1166	Clutch Linkage
55	1	WPD-1043	Black Nylon Spacer .118" Thick
56	1	STOF-0804	Spacer, 3/8"OD, 1/4"ID, 3/8" Long, Alum
57	1	WPD-1167	10-32 Shoulder Bolt, 3/8" Long

# CARRIAGES / MODULAR DRIVE SYSTEM

Two carriages are available for the **Modular Drive System** when using BUG-O Aluminum Rigid and Semi-Flex Rails. Both carriages are made of a high-strength, lightweight aluminum alloy, with wheels that ride in opposed recessed rail grooves.

The MPD-1065 Releasable 12" Carriage can be placed anywhere on the track by using the knob located on the side of the carriage, which engages or disengages the wheels from the rail. The MPD-1055 18" Carriage provides an extended deck for mounting accessories, wire feeder, etc. The pinion from the drive unit engages the rack on the rail, providing positive drive in all positions. On each carriage, one set of wheels is adjustable to allow for smooth, accurate travel. All wheels contain permanently lubricated, sealed bearings and their steel components are plated to resist corrosion.



1 2 3 4	QTY 2 2 2 1	PART NO. BUG-1984 FAS-0545 MPD-1045 MPD-1049	DESCRIPTION External Adj Leg & Wheel Assembly Soc Hd Cap Scr 10-32 x 1/2 Lg Fixed Leg & Wheel Assembly Handle, Black	5	
-	ı		*		<del>"</del> 2
5	1	MPD-1059	Knob Screw (Included w/carriage)		
6	1	MPD-1066	Carriage		; 
					<b>3</b>

# MPD-1055 CARRIAGE 18" (457 mm) 150 lb (67.5 kg) Carrying Capacity

## PARTS LIST / EXPLODED VIEW

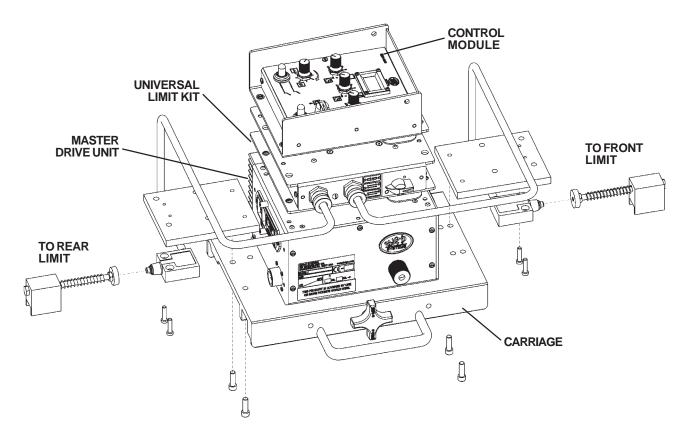
			DECODIDATION 5
<u>ITEM</u>	<u>QTY</u>	PART NO.	DESCRIPTION
1	3	BUG -1984	External Adj Leg &
			Wheel Assembly
2	3	BUG-2956	Fixed Leg & Wheel
			Assembly
3	4	FAS-0545	Soc Hd Cap Scr
			10-32 x 1/2 Lg
4	2	MPD-1049	Handle, Black
5	1	MPD-1055-PNT	Carriage 18", Painted
			3
			4
			<u> </u>

# MDS-1055 UNIVERSAL LIMIT KIT

The MDS-1055 Universal Limit Kit is an accessory that installs between the Master Drive Unit and any of the three control modules: the \*MDS-1001 Straightline, the MDS-1003 Stitch and the MDS-1005 Weaver Control Module. This limit kit adds the ability to CYCLE between limits, STOP AT LIMIT, or RAPID RETURN. All existing functions of the control modules are maintained.

#### **CYCLE MODES:**

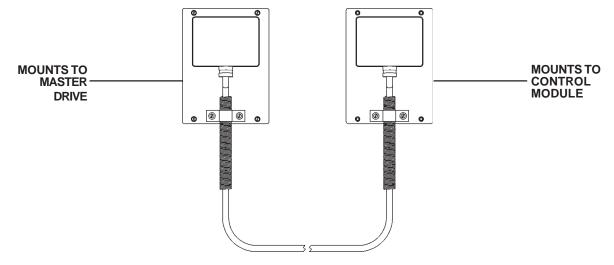
- a) CYCLE Cycles between two limits. Limit contact does not turn off the weld contactor.
- b) STOP AT LIMIT Limit contact in the direction of travel set by the control module Carriage Travel Switch will stop motion and turn off the weld contactor. The Carriage Travel Switch will reverse the travel direction and start motion away from the contacted limit. The weld contactor will not automatically turn back on when the machine exits a limit.
- c) RAPID RETURN The machine will run at the preset welding speed in the direction set by the Carriage Travel Switch on the control module until it hits a limit. When this limit is hit, the machine will turn off the weld contactor, reverse direction, and travel at full speed to the opposite limit. Upon reaching the limit, the machine stops.



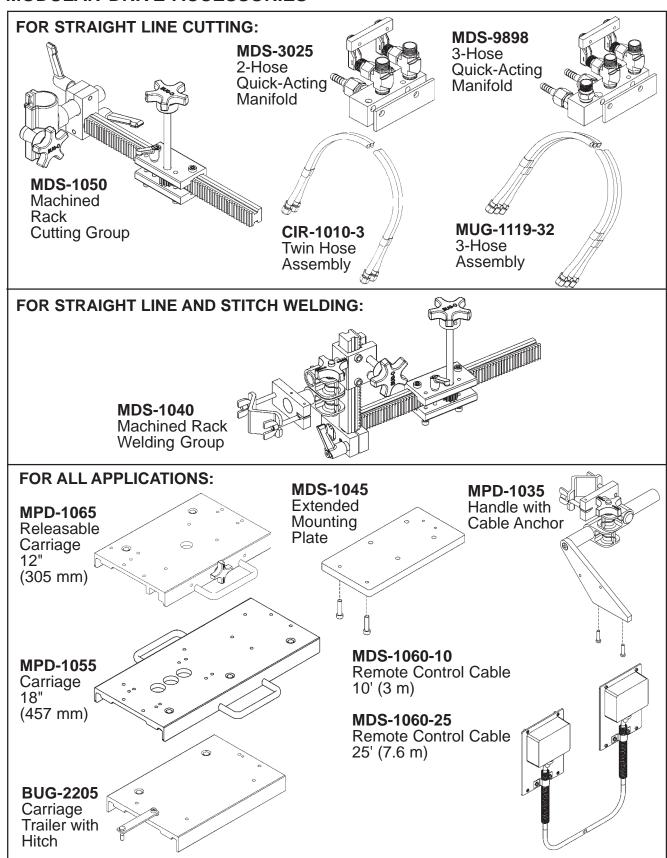
<sup>\*</sup> When using the MDS-1055 Universal Limit Kit with the MDS-1001 Straight Module, the Cycle Selector on the Straight Module must be set to **BASIC FORWARD/REVERSE** mode for the machine to operate. Use the mode selector on the MDS-1055 Universal Limit Kit to set the limit mode.

# MDS-1060-\_ REMOTE CONTROL CABLE

The optional Remote Control Cable allows the operator to perform work in confined areas where it is difficult to reach the controls. To use the remote cable, detach the control module from the master drive. Fasten the Master Drive Adaptor Plate to the drive unit using the four 8-32 x 3/8 long captive screws provided with the remote cable. Attach the Control Module Adaptor Plate to the control module using the control module's captive screws. The Master Drive Unit is now ready for remote control.

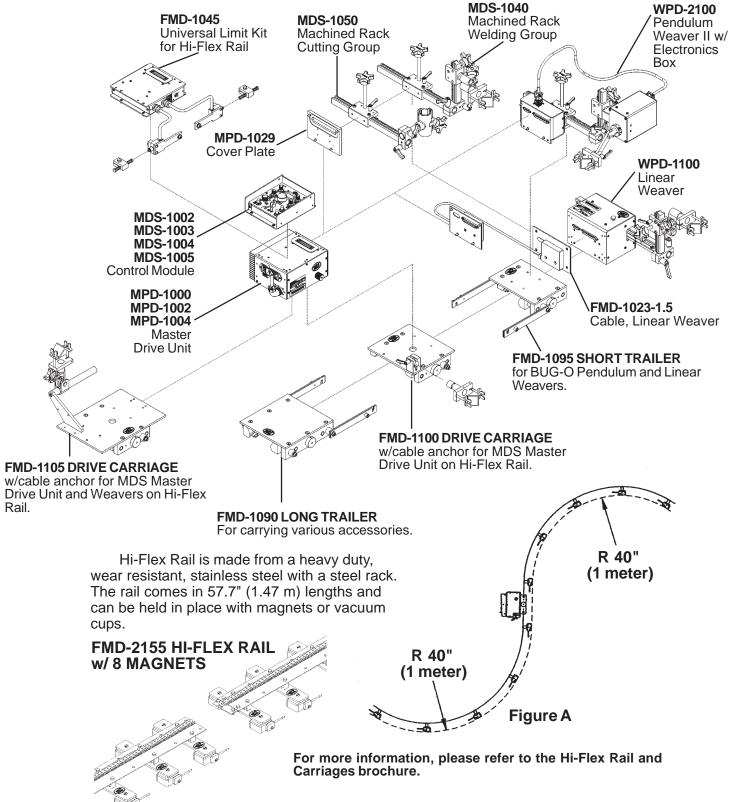


### MODULAR DRIVE ACCESSORIES



#### HI-FLEX RAIL AND CARRIAGES

The Hi-Flex Rail Carriages are designed to be used with the Modular Drive System as shown below. They have a built-in quick release for mounting and removal at any point along the rail. The carriages run on Hi-Flex Rail, from a straight to a 40" (1 m) radius inside or out (see Figure A).



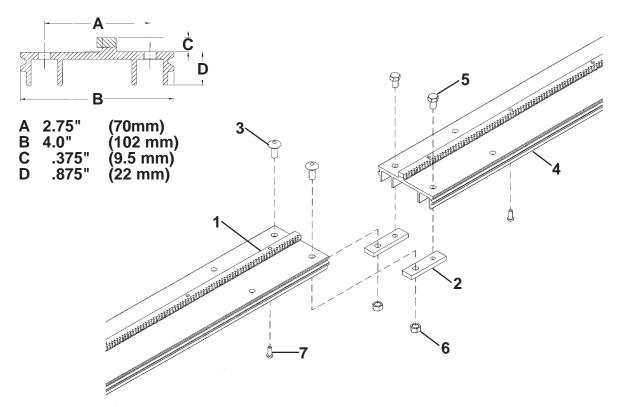
#### **ALUMINUM RIGID RAIL**

**ALUMINUM RIGID RAIL** is a high quality alloy, rigid section made to the machine tool tolerance shown in the sectional view below. The carriage drive pinion meshes with a machined gear rack that is mounted on the rail. The wheels of the carriage travel in opposed grooves at either side of the rail, locking the carriage to the rail. Heavy duty [H.D.] aluminum four-legged rigid rail is supplied in two lengths: ARR-1080 [93-1/2" (2.37 m)] called 8' (2.37 m) rail and ARR-1085 [46-1/2" (1.18 m)] called 4' (1.18 m) rail - see insert below. Extra heavy duty aluminum four-legged rigid rail: ARR-1250 [93-1/2' (2-37 m)] called 8' (2.37 m) rail and ARR-1200 [46-1/2" (1.18 m)] called 4' (1.18 m) rail, is also available.

#### **RAIL FOR LONGER SPANS:**

When unsupported rail paths longer than 93-1/2" (2.37 m) nominal 8' (2.37 m) rail are required, multiple sections of standard rail are mounted on plate, channel or box sections.

### ARR-1080 / H.D. ALUMINUM RIGID RAIL 8' (2.37 m)

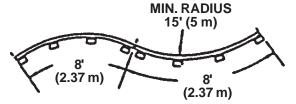


#### **Parts List**

<b>ITEM</b>	<b>QTY</b>	PART NO.	<u>DESCRIPTION</u>
1	1	ARR-1006	Rack
2	2	ARR-1027	Splice Bar
3	2	ARR-1028	Carriage Soft
4	1	ARR-1081	Rail-Extrusion
5	2	FAS-0375	Hex Hd Cap Scr 5/16-18 x 1/2
6	2	FAS-1370	Hex Nut 5/16-1 8
7	16	FAS-1445	S.T. Pan Hd Scr 10-32 x 1/2

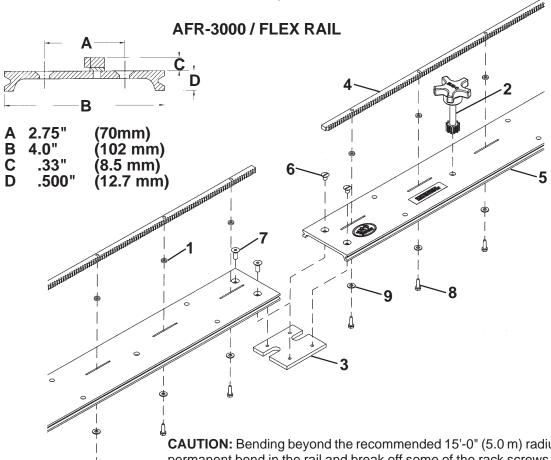
#### **FLEX RAIL**

FLEX RAIL can be bent inside or outside to a minimum radius of 15' (5.0 m) or 30' (10.0 m) diameter without permanent deformation.



AFR-3000 FLEX RAIL replaces the old AFR-1000, 1010, 1020 and the later AFR-2000 rails. All the rack-mounting holes on the AFR-3000 Semi-Flex Rail are slotted so that the rack can slide along the rail. The length of the slots has been increased so that the rails can now be leapfrogged around a complete circle. The tension of the screws holding the rack on the rail is adjusted so that the rack can be moved along the rail with the AFR-2001 Rack-Adjusting Tool.

NOTE: Use at least four attachments (magnets or vacuum cups) on each FLEX RAIL.



**CAUTION:** Bending beyond the recommended 15'-0" (5.0 m) radius may put a permanent bend in the rail and break off some of the rack screws.

<b>Parts</b>	List
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<u>ITEM</u>	<b>QTY</b>	PART NO.	<b>DESCRIPTION</b>
1	16	AFR-1015	Spacer Washer
2	1	AFR-2001	Rack Adjusting Tool
3	1	AFR-3002	Splice Plate
4	1	AFR-3006	Rack
5	1	AFR-3009	Extrusion, Punched
6	2	FAS-0855	Flt Hd Soc Scr 1/4-20 x 1/2
7	2	FAS-0955	Flt Hd Soc Scr 1/4-20 x 1/2
8	16	FAS-1446-HW	S.T. Slotted Hex w/Washer 10-32 x 5/8
9	16	WAS-0230	# 10 Washer

#### STANDARD MAGNET ASSEMBLIES

**MAGNET PLATE ASSEMBLIES** mount ARR rail quickly and conveniently right on the work surface. Magnets cannot exert maximum pull on dirty material. Remove excessive paint, scale and rust from the area on which the magnets will be placed.

**KEEP MAGNETS CLEAN -** before positioning, wipe off magnetic particles which adhere to the poles.

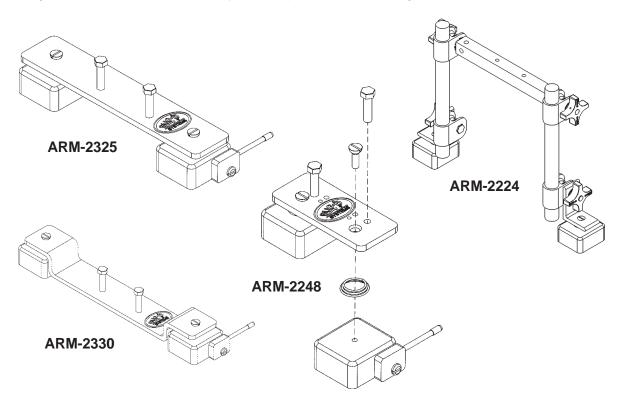
For **MAXIMUM HOLDING POWER** on swivel magnets, press down on top of each side of magnet.... then rotate until it holds firmly. The magnet will retain its magnetism indefinitely - to preserve the magnet casing, keep torch 4" (100 mm) away from magnets when burning. Use various thicknesses of keepers to decrease the magnetic pull when required.

**ARM-2224 -** Universal magnet assembly has extension legs which can be adjusted to fit a wide variety of shapes. The universal attachments to the cross bar may be used as shown below or any position on the bar. The legs adjust up and down. This magnet assembly holds up to 150 lbs. (68 kg) on a flat, clean steel surface.

**ARM-2248 -** Magnet bar, short; compact for positioning in hard-to-reach or restricted areas. This assembly holds up to 200 lbs. (91 kg) on a flat, clean steel surface.

**ARM-2325 -** Magnet bar, swivel with release; recommended for all applications, combines maximum strength and versatility. This assembly holds up to 250 lbs. (113 kg) on a flat, clean steel surface.

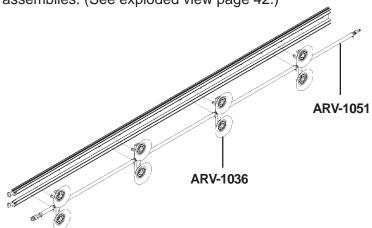
**ARM-2330 -** Low profile magnet assembly with quick release lever; for use on jobs that have height restrictions. This assembly holds up to 200 lbs. (91 kg) on a flat, clean steel surface.



**NOTE:** Use four magnet assemblies per 8' (2.37 m) section and use two magnet assemblies per 4' (1.18 m) section.

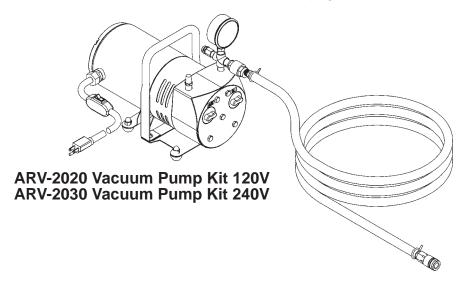
# **VACUUM SUPPORT KIT**

The standard Vacuum Support Kit, ARV-1080 or ARV-1085 consists of four (4) bars (with 8 cups) and associated hose and fittings. Some applications may require additional ARV-1036 Vacuum Support Bar assemblies. (See exploded view page 42.)



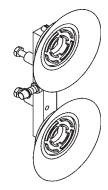
### **ARV-1102 Vacuum Support Kit**

Vacuum bars require a source of vacuum, which is provided by a Vacuum Pump Kit (ARV-1020 [120 VAC]; ARV-1030 (220 VAC). (See page 42 exploded view.)



# **VACUUM SUPPORT KIT (CONT'D.)**

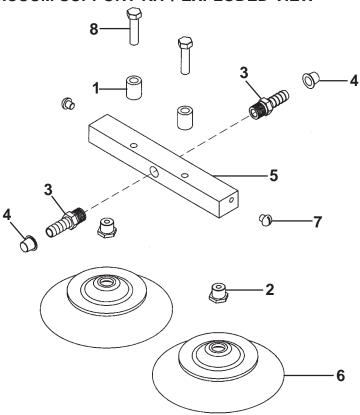
#### **ARV-1036 INTERMEDIATE VAC SUPPORT BAR**



VACUUM CUPS are used for mounting the rail to the workpiece when magnet bars will not hold. EXAMPLE: Stainless steel or nonferrous surfaces. The surface must be smooth and nonporous.

Each vacuum bar is fitted with two (2) cups and will exert a maximum pull of 100 lbs. (45 kg).

#### ARV-1036 VACUUM SUPPORT KIT / EXPLODED VIEW



#### ARV-1036 VACUUM SUPPORT KIT / PARTS LIST

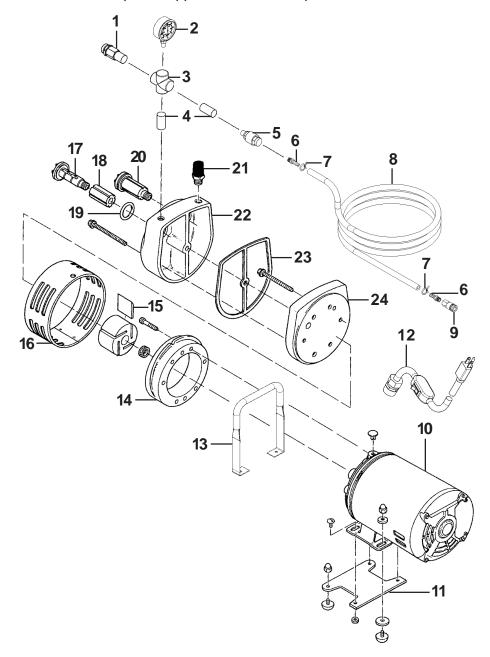
<u>ITEM</u>	<u>QTY</u>	<u>PART NO.</u>	<u>DESCRIPTION</u>
1	2	ARR-9008	Spacer Tube
2	2	ARV-1034	Choke Nipple
3	2	ARV-1107	3/8 Hose Barb x 1/4 NPT-M
4	2	ARV-1109	Protective Cap
5	1	ARV-1111	Support Bar
6	2	ARV-1116	Vacuum Cup (Silicone)
7	2	FAS-0252	Rnd Hd Scr 1/4-20 x 1/4
8	2	FAS-2372	Hex Hd Cap Scr 5/16-18 x 1-1/4

**NOTE:** Keep flame or arc at least 4"(100 mm) away from vacuum cups. Vacuum cups can be used on preheated material to 600° F (318° C). Each vacuum cup exerts a maximum pull of 50 lbs. (22.5 kg).

### **VACUUM PUMP / EXPLODED VIEW**

# ARV-2020 VACUUM PUMP KIT, 120VAC 60HZ/1PH ARV-2030 VACUUM PUMP KIT, 220 VAC 50 HZ/1PH

The **VACUUM PUMP KITS** are 1/6 HP units that provide 15" (381 mm) Hg on continuous duty. The ARV-2020/2030 Pump will support 30 vacuum cups.



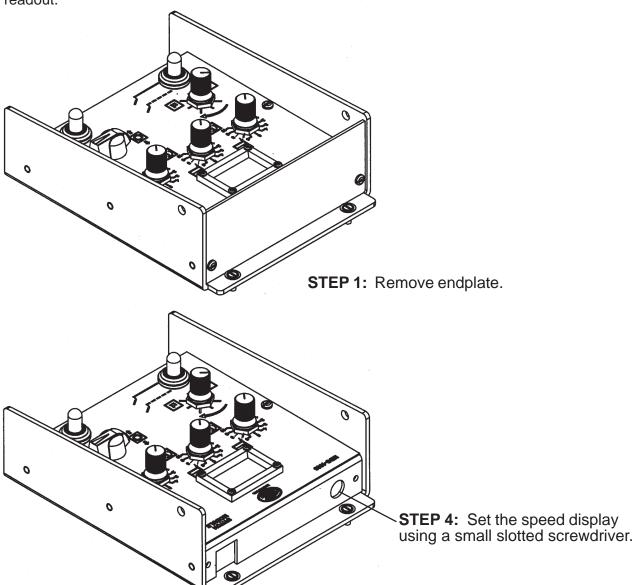
A Repair Kit ARV-1029 is available for the ARV-2020 and ARV-2030 pumps. The kit contains (4) vanes, (1) body gasket, filter felts for the muffler, oiler filter, and oiler wick, a cover gasket and separator felt for the oiler filter.

# **VACUUM PUMP / PARTS LIST**

<b>ITEM</b>	<b>Quantity</b>	PART NO.	<u>DESCRIPTION</u>
1	1	ARV-2017	1/4" Brass Vacuum Relief Valve
2	1	ARV-2014	Vacuum Gage
3	1	ARV-2018	1/4" NPT Union Cross, Female
4	2	ARV-2012	1/4" NPT Nipple
5	1	ARV-2016	1/4" NPT Brass Check Valve, F
6	2	ARV-1107	3/8" Hose Barb x 1/4" NPT-M
7	2	ARV-1005	11/16" x .112 Thk
8	1	ARV-1004-P	Hose 3/8" ID x 11/16" OD
9	1	ARV-1012	Female Quick Connector
10	1	ARV-2019	Pump
11	1	ARV-1999	Foot Support
12	1	ARV-2021	120 VAC Power Cord w/Switch
13	1	ARV-2013	Handle
14	1	ARV-2011	Body
15	4	ARV-2010	Vane
16	1	ARV-2009	Shroud
17	2	ARV-2003	End Cap
18	2	ARV-2004	Felt
19	2	ARV-2005	O-ring
20	2	ARV-2002	End Cap Assembly
21	1	ARV-2001	Filter/Muffler
22	1	ARV-2006	Muffler Box
23	1	ARV-2007	Gasket
24	1	ARV-2008	End Plate

### **DIGITAL READOUT CALIBRATION**

Internal Control Module adjustments enable the user to change between the factory-set cm/min and in/min. The display can also be recalibrated, if required, to give an accurate speed readout.



**STEP 2:** Set Switch 1 & 2:

	SW 1	SW 2
in/min	Down	Down
cm/min	Up	Down

**STEP 3:** Apply power to the Modular Drive. Maximize the tractor speed using the Control Module front panel.

**STEP 5:** Reinstall endplate.

#### MODULAR DRIVE SYSTEM TROUBLESHOOTING GUIDE

The Modular Drive System allows the user to mix and match components to custom build a machine for an application. The resulting ability to replace and remove individual components while trouble-shooting significantly reduces the time and effort required to troubleshoot the system. The recommended troubleshooting procedure is as follows:

- 1) Verify that there are no loose electrical or mechanical connections.
- 2) Verify that the welding power source is properly grounded and its ground clamp is attached to the workpiece.
- 3) Ensure the High Frequency Warnings in the front of this IPM are not being violated.
- 4) When possible, swap out each component in the system one at a time with a known good component. For example, replace the Control Module on a defective machine with the Control Module from a working machine. Often, this will pinpoint the defective component quickly. If the defective component is a Weaver Drive or a Master Drive, troubleshoot the drive to a circuit board level using step 5 and/or 6 below.
- 5) Remove all attached components. This includes the Remote Control Cable and Universal Limit Kit. All attached components are removed to limit the number of components affecting the operation and complexity of the system. Assemble a base system composed of a Control Module and a Master Drive. Test the base system. If the base system does not work, troubleshoot the base system to a circuit board level using the Base System Test Procedure. If possible, test the Control Module by swapping it with a known good Module.
- 6) If the system had a Weaver Drive, install it and retest the system. If the system does not work, troubleshoot the system to a circuit board level using the Base System Test Procedure.
  NOTE: The weaver failure can result from a faulty Control Module, Master Drive or Weaver Drive because they all interact. Use the Base System Test Procedure to find the faulty component.
- 7) Some components require special attention when troubleshooting and have their own trouble shooting section. These components are:

#### Universal Limit Kit

Perform any relevant troubleshooting section as required before proceeding to the base system test procedure. The special troubleshooting sections are located after the Base System Test Procedure.

**8)** Finish installing the components one at a time. Test the system after each installation in order to identify the problem components.

PROBLEM	POSSIBLE CAUSE	TEST	BASE SYSTEM TEST PROCEDURE / REMEDY
Speed display is not lit and tractor does not run.	Power switch is OFF.	1A	Turn ON the main ON/OFF switch located in the power entry module. (see Figure 1)
	No power to machine.	1B	Verify the power cord is OK and the correct voltage exists at the outlet.
	Blown fuse.	1C	Unplug the power cord. Check the machine's power input fuse(s). The fuse(s) is located in the power entry module and is accessible without opening the case.
	Faulty accessory attached to the master drive accessory port.	1D	Remove any accessory plugged into the master drive accessory port (see figure 2). Plug in the power cord and turn on the main power.
	decededly port.		a) If the speed display does not light, proceed with test 1E
			b) If the speed display lights, install the connector cover on the accessory port. <b>NOTE:</b> FAILURE TO INSTALL THE CONNECTOR COVER ON THE ACCESSORY PORT AFTER COMPLETING THIS TEST MAY CAUSE SERIOUS INJURY FROM ACCIDENTAL ELECTRICAL SHOCK.
			Set the tractor for continuous forward motion at full speed. If the control module has any type of motion enable switch, turn it to enable.
			1) If the tractor does not work properly, proceed with step 2A.
			If the tractor operates correctly, the accessory removed from the accessory port is defective.
	Faulty power entry module.	1E	Remove the connector cover or any attached accessory from the master drive accessory port (see Figure 2). Verify the power line voltage is on the two outer pins of the three pin connector (see Figure 2). The center pin is chassis ground. <b>NOTE:</b> INSTALL THE CONNECTOR COVER ON THE ACCESSORY PORT AFTER COMPLETING THIS TEST. FAILURE TO INSTALL THE COVER MAY CAUSE SERIOUS INJURY FROM ACCIDENTAL ELECTRICAL SHOCK.
			If the voltage is not present, rerun tests 1A, 1B, 1C, 1D and 1E. A second failed 1E test indicates bad internal AC wiring or a defective power entry module. Open the master drive case (see Figure 3). Examine the AC wiring and rewire at fault or replace the power entry module assembly. <b>NOTE:</b> The replacement power entry module is provided with the accessory port's three pin AC connector prewired.

PROBLEM	POSSIBLE CAUSE	TEST	BASE SYSTEM TEST PROCEDURE / REMEDY
	Defective RFI filter.	1F	Disconnect the two RFI filter output wires (see Figure 1). Turn on the main power. Verify the power line voltage exists on the two output wires. Reconnect the wires. Replace the RFI filter if the power line voltage is not present.
	Bad power supply.	1G	Turn on the main power. The green LEDs L1 and L2 (see Figure 1) will light if the power supply is OK.
			If the LEDs are off, unplug the power supply output connector (see Figure 1). The connector wiring is: White & RED is +15 V DC (+/-2V). White & Black is DC ground. White & Orange is -15 V DC (+/-2V). Measure the voltages at the connector.
			a) A bad voltage indicates a defective supply. Replace the supply.
			b) Correct voltages indicate the power supply is OK, however, there is a short in the equipment. Plug in the power supply output connector. Perform test 1H.
	Short circuit.	1H	The Green LEDs L1 and L2 will light when the short is removed. Unplug the following and monitor the LEDs to see if the short is removed: 1) The control module 2) The speed card input power connector (see Figure 1). 3) All connectors attached to the interconnect card (see Figure 1), except the connector from the supply.
			If L1 and/or L2 never turned on, the interconnect card is bad. Replace the board.
No tractor speed control and display is lit.	Operator Error (Stitch Control Module).	2A	Set the MODE switch to CONTINUOUS WELD and the CARRIAGE TRAVEL switch to STOP. Turn the SPEED CONTROL clockwise. Proceed to step 2C if the display does not increase. If the display does increase, then turn the CARRIAGE TRAVEL switch to FORWARD. Open the master drive case (Figure 3) and proceed to step 2D if the tractor does not move forward.
	Operator Error (Weaver Control Module).	2B	Set the MODE switch to RUN, the CARRIAGE TRAVEL switch to STOP and the START/STOP switch to START. Turn the SPEED CONTROL clockwise. Proceed to step 2C if the display does not increase. If the display does increase, then turn the CARRIAGE TRAVEL switch to FORWARD. Open the master drive case (Figure 3) and proceed to step 2D. If the tractor does not move forward.
	Bad DC power.	2C	Open the master drive case (Figure 3). Unplug the power supply output connector (see Figure 1). The connector wiring is: White & Red is +15 V DC (+/-2 V). White & Black is ground. White & Orange is -15 V DC (+/-2 V). Measure the voltages at the connector.

PROBLEM	POSSIBLE CAUSE	TEST	BASE SYSTEM TEST PROCEDURE / REMEDY
			A missing or bad voltage indicates a bad supply. Replace the supply.
	Faulty motor wiring.	2D	Check the wires from the speed card to the motor for faults. Rewire if needed.
	Faulty motor.	2E	Disconnect the motor leads. Apply 2 to 8 volts DC across the motor leads. Verify that the motor spins.
	Faulty control module, speed card, or motor.	2F	Install one voltmeter lead on TP4 and the other lead on TP5. Turn on the main power. Set the control module for continuous forward tractor motion. If the control module has any type of motion enable switch, turn it to enable. Rotate the tractor speed control knob while observing the voltmeter output. It is possible to vary this voltage between 0 and 8 Volts DC using a good control module.
			a) If the voltage does not vary, replace the control module card.
			b) If the voltage does vary, turn the machine OFF and then ON using the main power switch. Observe LED L5. L5 should light for a moment or two during power-up while safety circuits hold the tractor OFF until full power is reached. L5 should then turn off indicating power has been applied to the motor and motion should start.
			1) If the L5 never lights, replace the speed card.
			<ol> <li>If the L5 turns on, turns off, and then turns on again, check for shorted motor connections. If none are found, replace the speed card.</li> </ol>
			3) If the L5 turns on and then stays on, check that the control module is set up as defined above and retest 2F. A second failure indicates a bad speed card.
			4) If L5 turns on and then off and the motor doesn't start turning, turn the tractor speed up. If the motor does not begin to turn, check the motor to speed card wiring for faults and repair as needed. If the motor still fails to turn, replace the speed card.
Stitch mode on control module	Bad control module or bad tractor speed card.	3A	If the speed and direction work in CONTINUOUS mode, then the control module is bad.
does not work.			If the speed and direction do not work in CONTINUOUS mode, go to test 2A.

PROBLEM	POSSIBLE CAUSE	TEST	BASE SYSTEM TEST PROCEDURE / REMEDY
Tractor moves a short distance and then stops.	High Frequency Interference.	4A	Turn off the welder or plasma unit. The unit should operate normally.
	Carrying too much weight.	4B	Verify the load placed on the carriage does not exceed the factory rating.
	Brake is dragging.	4C	Remove the unit from the track and set the controls to forward tractor motion. If the pinion motion stops after a short time, or a check shows that the weight placed on the machine is not excessive, then the problem is most likely brake related. Return the machine for repair.
Linear Weaver does not move.	Bad control card or bad weaver.	5A	Set the weaver control module MODE SELECT switch to NO WEAVE and the START/STOP switch to START. Turn the weave speed up to max. Continuously move the STEERING CONTROL knob clockwise and then counter clockwise. This should cause the weaver arm to move back and forth.  a) If the arm moves, proceed to step 6A.  b) Unbolt and disconnect the weaver box from the modular drive accessory port (see Figure 2). Open the master drive case (see Figure 3). Install one voltmeter lead on TP6 and the other lead on TP7 (see Figure 1). Turn on the unit.  Set the weaver control module MODE select switch to RUN (no weave) and the START/STOP switch to START.  If the voltage reading is less than 2 V DC, adjust the STEERING pot on the control module until the reading is greater than 2 V DC.
			<ol> <li>If the pot adjustment will not produce at least 2 V DC on the voltmeter, replace the control module card.</li> <li>If the voltmeter displays above two volts, with or without pot adjustment, replace the weaver speed card.</li> </ol>
Linear Weaver moves in one direction only or moves erratically.	Bad control card, bad weaver speed card, or loose set screws on the servo pot's flexible coupling (coupling is used on WPD-1000 only).	6A	On the WPD-1000 linear weaver only, tighten the set screws on the servo potentiometer's flexible coupling. This part can be accessed by removing the WPD-1000 linear weaver's side panel that is located closest to the clutch screw.  Set the weaver control module MODE SELECT switch to NO WEAVE and the START/STOP switch to START. Turn the WEAVE SPEED up to max. Continuously move the STEERING CONTROL knob clockwise and then counter clockwise. This should cause the weaver arm to move back and forth.

PROBLEM	POSSIBLE CAUSE	TEST	BASE SYSTEM TEST PROCEDURE / REMEDY
			a) If the weaver moves in one direction only, the weaver speed card is bad. b) If the arm weaves but the control module does not function correctly, the control module is bad.
Pendulum shaft does not move.	Bad control module, damaged power cable, bad speed board or bad capacitor board.	7A	Set the weaver control module MODE SELECT switch to RUN (no weave) and the START/STOP switch to START. Turn the WEAVE SPEED to maximum. Move the STEERING CONTROL knob clockwise and counter-clockwise. This should cause the pendulum shaft to move back and forth.  a) If the pendulum output shaft moves, then proceed to step 8A.  b) Listen very closely to the Pendulum Gearbox to see if the motor is turning. The gearbox is bad if the motor is turning but the output shaft does not turn.  c) Remove the cable from between the electronics box and the pendulum gearbox. Use a meter to verify the connections through the cable. For example, verify pin A to pin A continuity, pin B to pin B, etc.  d) Remove the pendulum weaver electronics box from the modular drive accessory port by removing 4 pan head screws (see Figure 2). Open the master drive case (see Figure 3). Install one voltmeter lead on TP6 and the other on TP7 (see Figure 1). Turn on the unit, set the weaver control module MODE SELECT switch to RUN (no weave) and the START/STOP switch to START.  If reading is less than 2 V DC, adjust the STEERING pot on the control module until the reading is greater than 2 V DC. Replace the control module if the pot adjustment will not produce at least 2 V DC on the voltmeter.  e) Reassemble the master drive case (see Figure 3). Open the pendulum electronics box by removing the 4 pan head screws. Install the back of the electronics box onto the master drive unit. Locate the 2 pin connector on the speed board. Place the voltmeter probes in the connector from the back. Set the control module as follows.  1) Set the MODE switch to any mode except RUN (no weave)  2) Set the WEAVE SPEED to 3.  3) Set the WEAVE SPEED to 3.  3) Set the WEAVE SPEED to maximum.  4) Set the RIGHT and LEFT DWELL to minimum.  5) Turn on the main power. Set the STOP/START switch to START to enable weaver motion.

PROBLEM	POSSIBLE CAUSE	TEST	BASE SYSTEM TEST PROCEDURE / REMEDY
			If the voltmeter reads 1.5 V DC or more, replace the gear motor box.  f) If the voltmeter reading is less than 1 V DC, unplug connector J1 from the speed board. Unplug connector JP1 from the capacitor board and plug it into J1 on the speed board. Redo test 7D.
Pendulum Weaver moves in one direction only or moves erratically.	Bad control card or bad speed card.	8A	Set the weaver control module MODE SELECTOR switch to NO WEAVE and the START/STOP switch to START. Turn the WEAVE SPEED up to max. Continuously move the STEERING CONTROL knob clockwise and then counter clockwise. This should cause the weaver arm to move back and forth.  a) If the weaver moves in one direction only, the weaver speed card is bad. b) If the arm weaves but the control module does not function correctly, the control module is bad.

The Modular Drive System is equipped with internal fault diagnostic LEDs and test Points 10 Speed troubleshooting as shown below. Test point evaluation should be performed by a qualified technician using a volt meter. If a qualified technician is not available, return the unit to the factory for repair. Always unplug the power cord before opening the case.

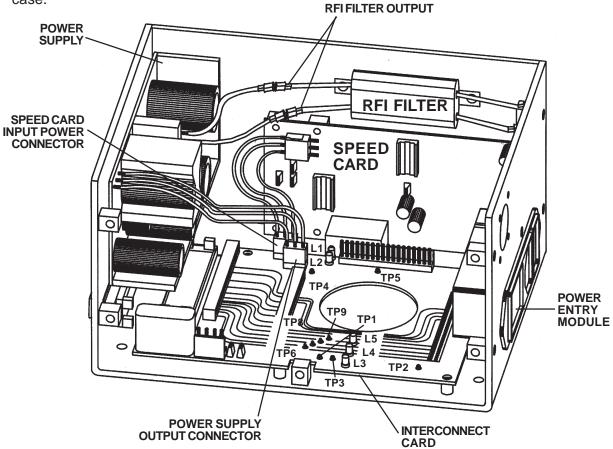


Figure 1. Troubleshooting Test Points

#### **TEST POINTS**

- TP1 -15V TP2 **GND** TP3 +15V
- TP4 **Tractor** + Speed Command TP5 **Tractor** - Speed Command
- TP6 Weaver + Speed Command
- TP7 **Weaver - Speed Command**
- TPB Height + Speed Command TP9 **Height** - Speed Command
- L1 -15v
- L2 +15V
- L3 **Height Off**
- L4 **Weaver Off**
- L5 **Tractor Off**

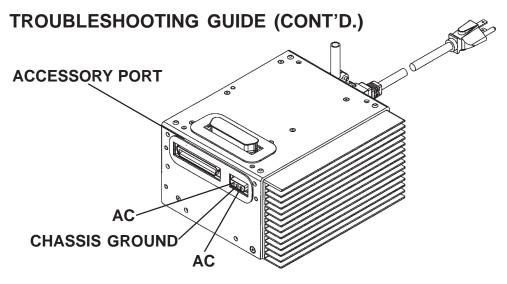
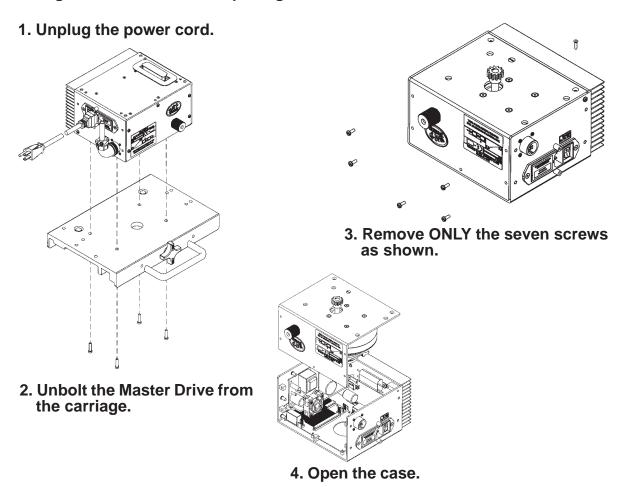


Figure 2. Master Drive Accessory Port

Figure 3. Procedure for Opening the Master Drive Case:



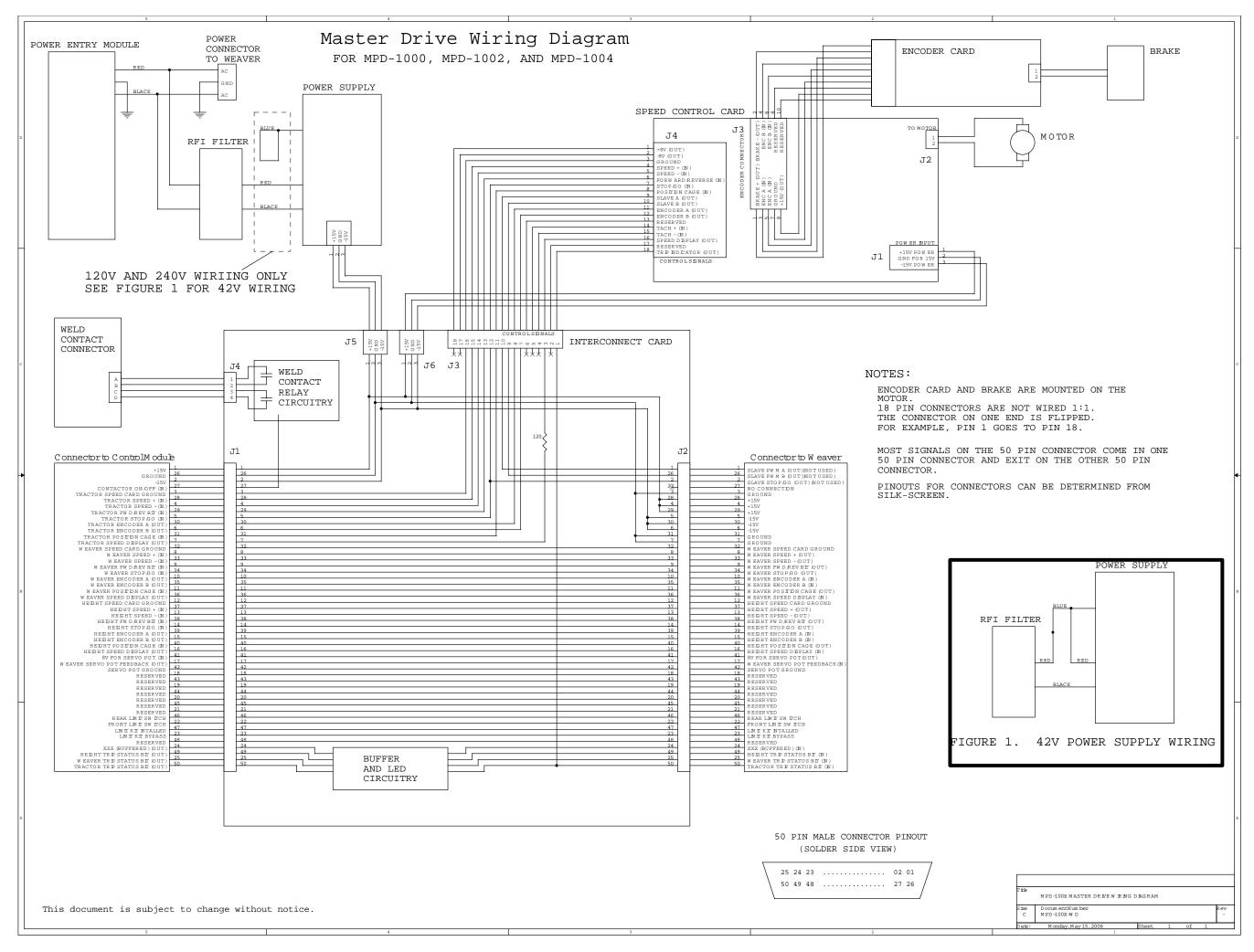
**CAUTION:** UNPLUG THE POWER CORD BEFORE OPENING OR CLOSING THE CASE OR SERIOUS INJURY MAY RESULT.

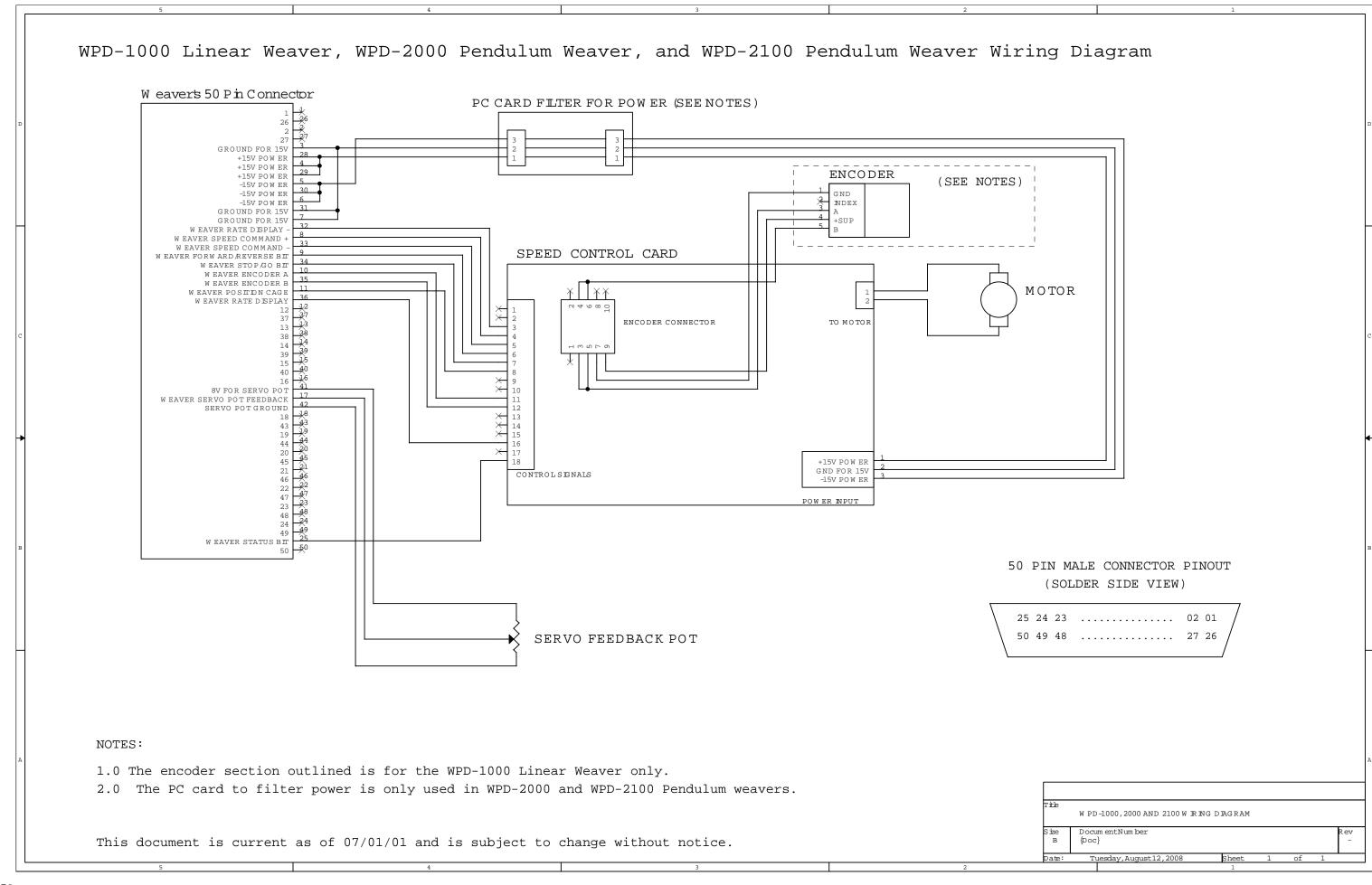
#### UNIVERSAL LIMIT KIT TROUBLESHOOTING

This Troubleshooting section details troubleshooting the Universal Limit Kit. See the **Modular Drive System Troubleshooting Guide** for troubleshooting all other components.

#### **Recommended Troubleshooting Procedure:**

- If using the Universal Limit Kit with the MDS-1001 Straight Module, the CYCLE SELECTION switch on the Control Module must be in the BASIC FORWARD/REVERSE position for the machine to operate property.
- 2) Perform steps 1 through 6 in the Modular System Troubleshooting Guide, The Master Drive, Control Module and Weaver Drive must be functioning correctly before proceeding.
- 3) Check for loose or damaged wires both internal and external to the Universal Limit Kit.
- 4) If the machine does not move at all, measure the voltage across each limit switch on the PC board while cycling the switch on and off. The voltage should toggle between 0 and 12V DC. If it does not, the limit switch or limit switch wiring is damaged.
  CAUTION: If using the MDS-1001 Straight Module with the Universal Limit Kit, the CYCLE SELECTION switch on the Control Module must be in the BASIC FORWARD/REVERSE position or the machine may not move.
- 5) If the machine turns around, stops, or starts unexpectedly, the Universal Limit Kit may be picking up RF noise from the welder. Move all of the welder cables away from the Universal Limit Kit, the limit switch wires and the Control Module.
- 6) If the previous steps did not fix the Universal Limit Kit, the PCB-1030 card is probably defective. Replace the card.





#### WARRANTY

### **Limited Warranty**

Model	
Serial No	
Date Purchased:	

For a period of twelve (12) months from delivery, BUG-O Systems warrants to the original purchaser (does not include authorized distributors), that a new machine is free from defects in material and workmanship and agrees to repair or replace, at its option, any defective parts or machine. This warranty does not apply to machines, which after our inspection, are determined to have been damaged due to neglect, abuse, overloading, accident or improper usage. All shipping and handling charges will be paid by customer.

BUG-O Systems makes no warranty of merchantability and makes no other warranty, expressed or implied, beyond the warranty expressly set forth above. Buyer's remedy for breach of warranty, hereunder, shall be limited to repair or replacement of non-conforming parts and machines. Under no circumstances shall consequential damages be recoverable.

#### **HOW TO OBTAIN SERVICE:**

If you think this machine is not operating properly, re-read the instruction manual carefully, then call your Authorized BUG-O dealer/distributor. If he cannot give you the necessary service, write or phone us to tell us exactly what difficulty you have experienced. BE SURE to mention the MODEL and SERIAL numbers.